HAWK

Single Board PC

User Manual

HAWK

User Manual

Document Part N°	0127-1030
Document Reference	HAWK\ 0127-1030.doc
Document Issue Level	1.0
Manual covers PCBs with the following Issue	1.x, (x is any alpha / digit)

Board name has been changed to HAWK effective 28/10/99.

All rights reserved. No part of this publication may be reproduced, stored in any retrieval system, or transmitted, in any form or by any means, electronic, mechanical, photocopied, recorded or otherwise, without the prior permission, in writing, from the publisher. For permission in the UK contact Blue Chip Technology.

Information offered in this manual is believed to be correct at the time of printing. Blue Chip Technology accepts no responsibility for any inaccuracies. The information contained herein is subject to change without notice. There are no express or implied licences granted herein to any intellectual property rights of Blue Chip Technology Ltd.

All trademarks and registered names acknowledged.

Blue Chip Technology Ltd.,
Chowley Oak, Tattenhall,
Chester, Cheshire,
CH3 9EX
Telephone : 01829 772000 Facsimile : 01829 772001

Amendment History

Issue Level	Issue Date	Author	Amendment Details
0.1	25/04/97	EGW	First Draft Issue
0.2	29/07/97	SEJ	Updated modifications
0.3	15/08/97	BH	Software section update
0.4	14/10/97	SEJ	Amendments see ECN 97/114
0.5	04/11/97	SEJ	Amendments see ECN 97/126
0.6	17/12/98	SO	Amendments see ECN 98/113
1.0	28/10/99	EW	Rename board HAWK – see ECN 99 / 098

INTRODUCTION 1

MANUAL OBJECTIVES 1
LIMITATIONS OF LIABILITY 1
PRECAUTIONS 2
ELECTRO-STATIC DISCHARGES 2
ON-BOARD BATTERY 2
RELATED PUBLICATIONS 3
TRADEMARKS 3

USER GUIDE 4

OVERVIEW 4
BOARD LEVEL FEATURES 5
CPU 5
PROCESSOR UPGRADE 6
SYSTEM MEMORY 6
SECOND LEVEL CACHE 7
BUS EXPANSION SLOTS 7
ELECTROMAGNETIC COMPATIBILITY 7
SPECIFICATION 9

HARDWARE DESCRIPTION 10

CHIPSET 10
82439HX XCELERATED CONTROLLER (TXC) 10
PCI/ISA IDE XCELERATOR (PIIX3) 11
UNIVERSAL SERIAL BUS (USB) 11
I/O CONTROLLER 12
IDE SUPPORT 12
SMC 37C932 SUPER I/O CONTROLLER 13
FLOPPY CONTROLLER 13
KEYBOARD INTERFACE 14
REAL TIME CLOCK, CMOS RAM AND BATTERY 14
CHIPS & TECHNOLOGY GRAPHICS SUBSYSTEM 15
DISPLAY CAPABILITIES 15
STANDARD VIDEO MODES 16
EXTENDED VIDEO MODES 17
HIGH REFRESH VIDEO MODES 17
FLAT PANEL EXTENDED VIDEO MODES 18
DIGITAL I/O CONNECTOR 19
BIOS 20
SYSTEM SETUP UTILITY 20

PCI SUPPORT *20*
ISA PLUG AND PLAY *20*
AUTO-CONFIGURATION CAPABILITIES *21*
ADVANCED POWER MANAGEMENT *21*
SLEEP MODE SUPPORT *22*
SECURITY FEATURES *22*
VIDEO BIOS 23
CONNECTING AN LCD TO HAWK 23
BACK PANEL CONNECTORS *26*
ON-BOARD CONNECTORS *26*
BUS CONNECTORS *27*
JUMPERS 27
CPU FREQUENCY SELECTION J4 & J5 ..... *27*
ON-BOARD VIDEO J6 ..... *29*
CMOS BATTERY SOURCE (CLEAR CMOS) J1 ..... *30*
TABLE OF JUMPERS *31*
STATUS LEDS *33*
USER-INSTALLABLE UPGRADES 34
SYSTEM MEMORY *34*
REAL TIME CLOCK BATTERY REPLACEMENT *35*
CPU UPGRADE *35*
GRAPHICS MEMORY UPGRADE *35*

SOFTWARE DESCRIPTION 36

BIOS SETUP - PROVISIONAL 36
OVERVIEW OF THE SETUP MENU SCREENS 36
MAIN SCREEN *36*
OVERVIEW OF THE SETUP KEYS *39*
STANDARD SETUP *40*
ADVANCED SYSTEM SETUP *42*
ADVANCED CHIPSET SETUP *47*
POWER MANAGEMENT SETUP *49*
PCI / PNP SETUP *52*
PERIPHERAL SETUP *56*
DISKONCHIP 2000 SUPPORT 59
PREFACE *59*
OPERATING THE DISKONCHIP *59*
INSTALLING THE DISKONCHIP 2000 ..... *59*
CONFIGURING THE DISKONCHIP 2000 AS THE BOOT DEVICE *60*
CONFIGURING THE DISKONCHIP 2000 AS THE FIRST DRIVE *61*
ADDRESS MAPS 62

MEMORY MAP *62*
I/O MAP *62*
PCI CONFIGURATION SPACE MAP *64*
INTERRUPTS & DMA CHANNELS *66*
CONNECTORS 67
BACK PANEL CONNECTORS *67*
ECP/EPP PARALLEL PORT P18 TOP (26 WAY HEADER) *67*
ETHERNET UTP CONNECTOR P22 (8 WAY RJ45) *69*
INTERNAL I/O HEADERS *69*
FLOPPY DISK DRIVE CONNECTOR P12 (34 WAY HEADER) *71*
POWER CONNECTOR P4 (34 WAY HEADER) *72*
BATTERY CONNECTOR P1 (4 WAY HEADER) *74*
BUS CONNECTORS *74*
ERROR MESSAGES 78
AMIBIOS ERROR BEEP CODES *78*
AMIBIOS ERROR CODES ON THE POST DISPLAY *79*
AMIBIOS ERROR MESSAGES *85*
ISA NMI MESSAGES *87*
PCI CONFIGURATION ERROR MESSAGES *88*
BOARD LAYOUT 89

COMPANY PROFILE

Blue Chip Technology is the leading specialist PC product manufacturer in UK/Europe.

Blue Chip Technology provides innovation with quality design and manufacturing from a single source.

Based in the North West, our purpose built complex contains one of the most advanced research and development facility, engineering workshop and production lines.

Specialising in the provision of industrial computing and electronic solutions for a wide range of UK and European organisations, Blue Chip Technology has one of the UK's largest portfolios of industrial PCs, peripherals and data acquisition cards. This extensive range of products, coupled with our experience and expertise, enables Blue Chip Technology to offer an industrial processing solution for any application. The HAWK Single Board PC is the latest addition to our portfolio, providing a cost effective product development and volume production tool for OEMs.

A unique customisation and specialised system integration service is also available, delivering innovative solutions to customers problems. The company's success and reputation in this area has led to a number of large design and manufacturing projects for companies such as BNFL, Aston Martin, JaguarSport and British Gas.

British Standards Institute approval (BS EN 9001) means that all of Blue Chip Technology's design and manufacturing procedures are strictly controlled, ensuring the highest levels of quality, reliability and performance.

Blue Chip Technology are also committed to the single European market and continue to invest in the latest technology and skills to provide high performance computer and electronic solutions for a world-wide customer base.

INTRODUCTION

MANUAL OBJECTIVES

This manual describes in detail the Blue Chip Technology HAWK Single Board processor card.

We have tried to include as much information as possible but we have not duplicated information that is provided in the standard IBM Technical References, unless it proved to be necessary to aid in the understanding of the HAWK.

The manual is sectioned and includes a User Guide which will help the non technical user to get the unit up and running. A Troubleshooting Guide is also included to help when things go wrong.

We strongly recommend that you study this manual carefully before attempting to interface with HAWK or change the standard configurations. Whilst all the necessary information is available in this manual we would recommend that unless you are confident, you contact your supplier for guidance.

Please be aware that it is possible to create configurations within the CMOS RAM that make booting impossible. If this should happen, clear the CMOS settings, (see the description of the Jumper Settings for details).

If you have any suggestions or find any errors concerning this manual and want to inform us of these, please contact our Customer Support department with the relevant details.

LIMITATIONS OF LIABILITY

In no event shall Blue Chip Technology be held liable for any loss, expenses or damages of any kind whatsoever, whether direct, indirect, incidental or consequential, arising from the design or use of this product or the support materials supplied with this product. If this product proves to be defective, Blue Chip Technology is only obliged to replace or refund the purchase price at Blue Chip Technology's discretion according to their Terms and Conditions of Sale.

PRECAUTIONS

It is imperative that precautions are taken to avoid electro-static discharges, or any maltreatment of the on-board battery.

ELECTRO-STATIC DISCHARGES

The devices on this card can be totally destroyed by static electricity. Ensure that you take necessary static precautions, ideally wear an approved wrist strap or touch a suitable ground to discharge any static build up. This should be repeated if the handling is for any length of time.

When carrying the board around, please place it into the non-conductive bag in which it came. This will prevent any static electricity build up.

ON-BOARD BATTERY

This board is fitted with a Lithium battery. Great care should be taken with this type of battery. Under NO circumstances should :

- the outputs be shorted
- be exposed to temperatures in excess of 100°C
- be burnt
- be immersed in water
- be unsoldered
- be recharged
- be disassembled

If the battery is mistreated in any way there is a very real possibility of fire, explosion, and harm.

RELATED PUBLICATIONS

The following publications will provide useful information related to the Standard Personal Computer and can be used in conjunction with this manual.

- IBM Personal Computer AT Technical Reference, 1502494, IBM, 1984.
- IBM Personal System/2 and Personal Computer BIOS Interface Technical Reference, 15F0306, IBM, 1987.
- The Programmers PC Sourcebook, Microsoft
- The Winn L. Rosch Hardware Bible, Brady
- PC104 Consortium Technical Specification

TRADEMARKS

IBM, PC, AT and PS/2 are trademarks of International Business Machines Corporation (IBM).

AMI Hi-Flex BIOS is a trademark of American Megatrends Inc.

Intel is a registered trademark of the Intel Corporation.

All 80x86 and Pentium processors are registered trademarks of Intel Corporation.

MSDOS and WINDOWS are registered trademarks of the Microsoft Corporation.

PC/104 is a registered trademark of the PC/104 Consortium.

USER GUIDE

OVERVIEW

The Blue Chip Technology HAWK single board PC sets new standards for integration of the latest advances in processor, memory, and I/O technologies. The HAWK complies with the new A5 form factor providing ISA, PCI and PC/104 bus interfaces on a single card. The A5 PC is an ideal platform for the increasing requirements of today's and tomorrow's embedded applications.

The flexible design will accept Pentium® processors operating at 75, 90, 100, 120, 133, 150, 166, 200 and 233 MHz, including MMX devices. The user may install 256 KB of asynchronous Cache, or 256 KB or 512 KB of Pipeline Burst Cache RAM in the form of a COAST (Cache On A STick) Module. The memory sub-system is designed to support up to 256MB of EDO DRAM (for improved performance) or standard Fast Page DRAM in standard 72-pin SIMM sockets. An SPGA socket provides upgrades for future OverDrive processors.

The HAWK single board PC utilises Intel’s Triton 82430HX PCIset to provide increased integration and performance over other single board PC designs. The Triton PCIset contains an integrated PCI Bus Mastering IDE controller with a high performance IDE interface allowing up to two IDE devices (such as hard drives, CD-ROM readers, etc.). The SMC 37C932 Super I/O controller integrates the standard PC I/O functions: floppy interface, two FIFO serial ports, one EPP/ECP capable parallel port, a Real Time Clock, keyboard and mouse (PS/2) controller.

The HAWK also provides for driving up to three external ISA 16 bit expansion slots.

In addition to superior hardware capabilities, a full set of software drivers and utilities are available to allow advanced operating systems such as Windows™ 95/98 to take full advantage of the hardware capabilities. Features such as bus mastering IDE, Windows™ 95/98-ready Plug and Play, Advanced Power Management (APM) are available for the HAWK.

BOARD LEVEL FEATURES

- SPGA socket supporting 75 - 233 MHz operation
- On-board 3.3 V CPU voltage regulator
- Intel Triton 82430 PCISet chipset:
  - 82439HX Xcelerated Controller (TXC)
  - PIIX3 PCI ISA IDE Accelerator (PIIX3) bridge
- 256KB or 512 KB PipeLine Burst Level 2 cache or 256 KB Asynchronous Level 2 cache using plug-in COAST connector
- Two SIMM sockets providing up to 256MByte of EDO or FPM DRAM
- C&T 65545/8 PCI CRT/LCD graphics controller with:
  - 1 MByte standard video memory
- ISA & PC/104 expansion busses
- SMC 37C932 I/O controller providing:
  - Dual PCI IDE interfaces
  - Dual floppy interface
  - EPP/ECP bi-directional parallel interface
- 4 on-board RS232 powered serial ports. One port selectable as RS422/485.
- Real-time clock with on-board battery
- PS/2 mouse and keyboard connectors
- Optional on-board Solid State Disk - Flash and SRAM inc. DOC
- Optional security microcontroller providing power monitoring and reset control or magstripe and Dallas Touchkey interfaces
- On-board status LEDs
- Drive for up to 3 ISA or 3 PC/104 cards

CPU

The HAWK single board PC is designed to operate with Pentium Processors running at 2.9, 3.3, 3.45 or 3.6 Volts. An on-board voltage regulator circuit provides the required voltage for the processor from the 5 volt output of a standard PC power supply. On-board jumpers enable the use of VRT(MMX) specified processors. Pentium processors which run internally at 75, 90, 100, 120, 133, 150, 166, 200 and 233 MHz are supported.

The Pentium processor maintains full backward compatibility with the 8086, 80286, i386™ and Intel486™ processors. It supports both read and write burst mode bus cycles, and includes separate 8 KB on-chip code and 8 KB data caches which employ a write-back policy. Also integrated into the Pentium processor is an advanced numeric co-processor which significantly increases the speed of floating point operations, whilst maintaining backward compatibility with Intel486™ math co-processor and complying to ANSI/IEEE standard 754-1985.

PROCESSOR UPGRADE

The HAWK single board PC has a 321-pin SPGA socket that provides users with an OverDrive processor upgrade path. OverDrive processors being developed for use will provide performance beyond that delivered by the originally installed Pentium Processor. MMX CPUs are also supported by HAWK.

SYSTEM MEMORY

The HAWK single board PC provides two 72-pin SIMM sites for memory expansion. The sockets support all sizes of memory from 4MB x 2 up to 128 x 2 single-sided or double-sided SIMM modules. Minimum total memory size is 8 MB and maximum is 256MB. **Note** The memory SIMM modules must be installed in pairs and must be of the same size and manufacture. It is recommended that a quality supply of SIMM modules be used to improve the performance and reliability. Please contact Blue Chip Technology for a recommended supply of Memory. Memory timing requires 70 ns fast page devices or, for optimum performance, 60nS EDO DRAM. If the memory bus speed is 60 MHz or slower (75MHz, 90MHz, 120MHz, 150MHz or 180MHz Pentium Processor speed), 70ns EDO DRAM may be used. If the memory bus speed is 66 MHz, 60 ns DRAM should be used. Additionally, 36-bit SIMM modules may be used to provide either standard parity operation or the parity circuitry can be used by the HX chipset to provide ECC correction. EDO DRAM is designed to improve DRAM read performance.

The two sockets are arranged in a bank which provides a 64-bit wide data path. There are no jumper settings required for the memory size or type, this is automatically detected by the system BIOS.

SECOND LEVEL CACHE

The Pentium processor's internal cache can be complemented by a second level cache using the COAST connector. Pipeline Burst SRAM provides performance similar to expensive Synchronous Burst SRAMs for only a slight cost premium over the slower performing Asynchronous SRAMs. With the Triton chipset, the performance level of Pipeline Burst and Synchronous SRAMs is identical.

BUS EXPANSION SLOTS

The HAWK is designed for use in an embedded application and provides expansion slots. There may be up to three ISA bus expansion cards and three PC/104 expansion cards. The PCB pads and mounting holes are inert, even so we recommend you fit insulating washers and pillars to avoid accidental short circuit of any adjacent tracks.

ELECTROMAGNETIC COMPATIBILITY

This product meets the requirements of the European EMC Directive (89/336/EEC) and is eligible to bear the CE mark.

It has been assessed operating in a Blue Chip Technology PC. However, because the board can be installed in a variety of computers, certain conditions have to be applied to ensure that the compatibility is maintained. Subject to those conditions, it meets the requirements for an industrial environment (Class A product).

- The board must be installed in a computer system chassis which provides screening suitable for an industrial environment.

- Any recommendations made by the computer system manufacturer/supplier must be complied with regarding earthing and the installation of boards.
- The board must be installed with the optional backplate securely screwed to the chassis of the computer to ensure good metal-to-metal (i.e. earth) contact.
- Most EMC problems are caused by the external cabling to boards. It is imperative that any external cabling to the board is totally screened, and that the screen of the cable connects to the metal end bracket of the board and hence to earth. It is recommended that round screened cables with a braided wire screen are used in preference to those with a foil screen and drain wire. Use metal connector shells which connect around the full circumference of the screen: they are far superior to those which earth the screen by a simple "pig-tail".
- The keyboard will play an important part in the compatibility of the processor card since it is a port into the board. Similarly, it will affect the compatibility of the complete system. A fully compatible keyboard must be used otherwise the complete system could be degraded. The keyboard itself may radiate or behave as if keys are pressed when subject to interference. Under these circumstances it may be beneficial to add a ferrite clamp on the keyboard lead as close as possible to the connector. A suitable type is the Chomerics type H8FE-1004-AS.
- Ensure that the screens of any external cables are bonded to a good RF earth at the remote end of the cable.

Failure to observe these recommendations may invalidate the EMC compliance.

Warning
This is a Class A product. In a domestic environment this product may cause radio interference in which case the user may be required to take adequate measures.

SPECIFICATION

HAWK Power Requirement	+5 V ± 5%	Required for processor operation.
	+12 V ± 5%	Only required with security / monitor micro-controller option.
	+3.3 V ± 5%	⎫ Not required for board operation.
	-5 V ± 5%	⎬ The ISA, PC104 & PCI voltage
	-12 V ± 5%	⎭ rails are linked, on board.
Typical System Consumption	35 Watts	Pentium 100, 16 MB RAM, 256 KB L2 cache, 3½" FDD, 540 MB HDD
Temperature	Non-Operating	-40°C to +70°C
	Operating	+0°C to +55°C (min. airflow of 200 lpm)
Shock	Non-Operating	Half sine, 2ms, 1 m drop
Vibration	Non-Operating	5 Hz - 500 Hz, 3.1 g RMS random
	Operating	10 Hz - 500 Hz, 1.0 g RMS random
EMC	Emissions	EN55022 (A)
	Immunity	EN50082-2 in a Blue Chip ICON Industrial PC Chassis
MTBF	Estimated	40,000 Hrs
Dimensions	Board only	338 x 122 mm

Power Consumption figures given are for a typical configuration.

This information is preliminary and is provided only as a guide to calculating approximate total system power usage when additional resources are added.

HARDWARE DESCRIPTION

CHIPSET

The Intel 82430HX PCIset consists of the 82439HX Xcelerated Controller (TXC) and one 82371SB PCI/ISA IDE Xcelerator (PIIX3) bridge chip.

82439HX XCELERATED CONTROLLER (TXC)

The 82439HX provides all control signals necessary to drive a second level cache and the DRAM array, including multiplexed address signals. The TXC also controls access to memory and generates snoop controls to maintain cache coherency. The TXC comes in a 324-pin BGA package and includes the following features:

- Microprocessor interface control
- Integrated L2 write-back cache controller
  - — Pipeline burst SRAM
  - — 256 KB direct-mapped
- Integrated DRAM controller
  - — 64 bit path to memory
  - — Support for EDO and fast page DRAM
  - — Parity and non-parity support
- Fully synchronous PCI bus interface
  - — 25/30/33 MHz bus speed
  - — PCI to DRAM > 100 MB/sec
  - — Up to four PCI masters in addition to the PIIX3

PCI/ISA IDE XCELERATOR (PIIX3)

The PIIX3 provides the interface between the on-board PCI and ISA buses and integrates a dual channel fast IDE interface capable of supporting up to four devices. The PIIX3 integrates seven DMA channels, one 16-bit timer/counter, two eight-channel interrupt controllers, PCI-to-AT interrupt mapping circuitry, NMI logic, ISA refresh address generation, and PCI/ISA bus arbitration circuitry together onto the same device. The PIIX3 comes in a 208-pin QFP package and includes the following features.

- Interface between the PCI and ISA buses
- Universal Serial Bus controller
  - — Host/hub controller
- Integrated fast IDE interface
  - — Support for up to four devices
  - — PIO Mode 4 transfers up to 16 MB/sec
  - — Integrated 8 x 32-bit buffer for bus master PCI IDE burst transfers
  - — Bus master mode
- PCI 2.1 compliant
- Enhanced fast DMA controller
- Interrupt controller and steering
- Counters/timers
- SMI interrupt logic and timer with fast on/off mode

UNIVERSAL SERIAL BUS (USB)

The HAWK single board PC features two USB ports as a factory installed option. The ports permit the direct connection of two USB peripherals without an external hub. If more devices are required, an external hub can be connected to either of the built-in ports. The motherboard fully supports the standard universal host controller interface (UHCI) and uses standard software drivers that are UHCI-compatible.

Features of the USB include:

- Self-identifying “hot pluggable” peripherals
- Automatic mapping of function to driver and configuration
- Support for isochronous and asynchronous transfer types over the same set of wires
- Support for up to 127 physical devices
- Guaranteed bandwidth and low latencies appropriate for telephony, audio, and other applications
- Error handling and fault recovery mechanisms built into protocol

NOTE

Computer systems that have an unshielded cable attached to the USB port might not meet FCC Class B requirements, even if no device or a low speed (sub-channel) USB device is attached to the cable. Use shielded cable that meets the requirements for high speed (fully rated) devices.

I/O CONTROLLER

IDE SUPPORT

The HAWK single board PC provides two independent high performance bus-mastering PCI IDE interfaces capable of supporting PIO Mode 3 and Mode 4 devices. The system BIOS supports Logical Block Addressing (LBA) and Extended Cylinder Head Sector (ECHS) translation modes as well as AT API (e.g. CD-ROM) devices on both IDE interfaces. Detection of IDE device transfer rate and translation mode capability is automatically determined by the system BIOS.

In the Windows™ 95/98 environment, a driver can allow the IDE interface to operate as a PCI bus master capable of supporting PIO Mode 4 devices with transfer rates up to 16MB/sec while minimising the system demands upon the processor. Normally, programmed I/O operations require a substantial amount of CPU bandwidth. In true multi-tasking operating systems like Windows™ 95/98, the CPU bandwidth freed up by using bus mastering IDE can be used to complete other tasks while disk transfers are occurring.

Microsoft will provide this driver for Windows™ 95/98, other software vendors may make drivers available for other operating systems.

Detailed information on the PCIset is available in the Intel 82430 PCISet data sheet.

SMC 37C932 SUPER I/O CONTROLLER

Control for the integrated serial ports, parallel port, floppy drive, RTC and keyboard controller is incorporated into a single component, the SMC 37C932. This component provides:

- Two powered NS16C550-compatible UARTs with send/receive 16 byte FIFO
- Multi-mode bi-directional parallel port
  - Standard mode; IBM and Centronics compatible
  - Enhanced Parallel Port (EPP) with BIOS/Driver support
  - High Speed mode; Extended Capabilities Port (ECP) compatible
- Industry standard floppy controller with 16 byte data FIFO (2.88 MB floppy support)
- Integrated Real Time Clock
- Integrated 8042 compatible keyboard controller

The 37C932 is normally configured by the BIOS automatically, however configuration of these interfaces is possible via the CMOS Setup program that can be invoked during boot-up. The serial ports can be enabled as COM1, COM2, or disabled. The parallel port can be configured as normal, extended, EPP/ECP, or disabled. The floppy interface is configurable.

Header connectors located near the top of the board allow cabling to use these interfaces.

FLOPPY CONTROLLER

The 37C932 is software compatible with the DP8473 and 82077 floppy disk controllers.

The floppy interface can be configured for 360 KB or 1.2 MB 5¼" media or for 720 KB, 1.44 MB, or 2.88 MB 3½" media in the BIOS setup. By default, the Floppy A interface is configured for 1.44 MB and Floppy B is disabled.

KEYBOARD INTERFACE

PS/2 keyboard/mouse connectors are located on the back panel side of the single board PC. A field exchangeable fuse protects the 5V lines to these connectors. Care must be taken to turn off the system power before installing or removing a keyboard or mouse, otherwise the fuse may rupture, and result in a return-to-base repair.

The integrated 8042 microcontroller contains the AMI Megakey keyboard/mouse controller code which, besides providing traditional keyboard and mouse control functions, supports Power-On/Reset (POR) password protection. The POR password can be defined by the user in the Setup program. The keyboard controller also provides the facility for a <CTRL><ALT><DEL> "hot key" sequence to perform a system software reset. It performs this by jumping to the beginning of the BIOS code and running the POST operation.

REAL TIME CLOCK, CMOS RAM AND BATTERY

The integrated Real Time Clock (RTC) is DS1287 and MC146818 compatible and provides a time of day clock, 100-year calendar with alarm features. The RTC can be set via the BIOS SETUP program. The RTC also supports 242 bytes of battery-backed CMOS RAM in two banks which is reserved for BIOS use. The CMOS RAM can be set to specific values or cleared to the system default values using the BIOS SETUP program. Also, the CMOS RAM values can be cleared to the system defaults by using a configuration jumper on the single board PC. The appendix lists the jumper configurations.

An on-board Lithium battery provides power to the RTC and CMOS memory. The battery has an estimated lifetime of three years if the board remains unpowered. When the system is powered up, power is drawn from the power supply to extend the life of the battery.

HAWK is Year 2000 compliant.

CHIPS & TECHNOLOGY GRAPHICS SUBSYSTEM

The HAWK single board PC is provided with a C&T 6554X graphics controller with 1 MB of graphics memory. Both CRT and LCD interfaces are provided. HAWK supports a wide variety of monochrome and colour Single-Panel, Single-Drive (SS) and Dual-Panel, Dual Drive (DD) passive STN and active matrix TFT/MIM LCD, EL and plasma panels. HAWK supports panel resolutions of 800x600, 1024x768 and 1280x1024. For monochrome panels, up to 64 grey scales are supported. Up to 226,981 different colours can be displayed on passive STN LCDs and up to 16M colours on 24 bit active matrix LCDs with HAWK.

The 6554X has a 32-bit graphics engine that provides acceleration for scaling the video display without compromising picture quality or frame rate. Hardware acceleration for graphics functions such as line draws, System-to-screen and screen-to-screen BitBLTs, ROPs, which optimise performance operation under Windows™ and other GUI environments.

DISPLAY CAPABILITIES

HAWK can support the following CRT/ LCD resolutions and colours simultaneously.

CRT MODE		MONO LCD	DD STN	9 BIT TFT	SIMULTANEOUS
RESOLUTION	**COLOUR**	**GREY SCALES**	**COLOURS**	**COLOURS**	**DISPLAY**
320x200	256/256K	61 / 61	256/226,981	256/185,193	Yes
640x480	16/256K	16 / 61	16/226,981	16/185,193	Yes
640x480	256/256K	61 / 61	256/226,981	256/185,193	Yes
800x600	16/256K	16 / 61	16/226,981	16/185,193	Yes
800x600	256/256K	61 / 61	256/226,981	256/185,193	Yes
1024x768	16/256K	16 / 61	16/226,981	16/185,193	Yes
1024x768	256/256K	61 / 61	256/226,981	256/185,193	Yes
1280x1024	16/256K	16 / 61	N/A	N/A	N/A

STANDARD VIDEO MODES

MODE # (HEX)	DISPLAY MODE	COLOURS	TEXT DISPLAY	PIXEL RES	H FREQ (KHZ)	V FREQ (HZ)
0+,1+	Text	16	40x25 40x25 40x25	360x400 320x350 320x200	31.5	70
2+,3+	Text	16	80x25 80x25 80x25	720x400 640x350 640x200	31.5	70
4	Graphics	4	40x25	320x200	31.5	70
5	Graphics	4	40x25	320x200	31.5	70
6	Graphics	2	80x25	640x200	31.5	70
7+	Text	Mono	80x25 80x25	720x400 720x350	31.5	70
D	Planar	16	40x25	320x200	31.5	70
E	Planar	16	80x25	640x200	31.5	70
F	Planar	Mono	80x25	640x350	31.5	70
10	Planar	16	80x25	640x350	31.5	70
11	Planar	2	80x30	640x480	31.5	70
12	Planar	16	80x30	640x480	31.5	70
13	Packed	256	40x25	320x200	31.5	70

EXTENDED VIDEO MODES

MODE # (HEX)	DISPLAY MODE	COLOURS	TEXT DISPLAY	PIXEL RES	H FREQ (KHZ)	V FREQ (HZ)
20	4bit linear	16	80x30	640x480	31.5	60
22	4bit linear	16	100x37	800x600	37.5	60
24	4bit linear	16	128x48	1024x768	48.5	60
24 I	4bit linear	16	128x48	1024x768	35.5	43
28 I	4bit linear	16		1280x1024	35.5	43
30	8bit linear	256	80x30	640x480	31.5	60
32	8bit linear	256	100x37	800x600	37.5	60
34	8bit linear	256	128x48	1024x768	48.5	60
34 I	8bit linear	256	128x48	1024x768	35.5	43
40	15bit linear	32K	80x30	640x480	31.5	60
41	16bit linear	64K	80x30	640x480	31.5	60
50	24bit linear	16M	80x30	640x480	27.1	51.6
60	Text	16	132x25	1056x400	30.5	68
61	Text	16	132x50	1056x400	30.5	68
6A, 70	Planar	16	100x37	800x600	38.0	60
72, 75	Planar	16	128x48	1024x768	48.5	60
72, 75 I	Planar	16	128x48	1024x768	35.5	43
76 I	Planar	16		1280x1024	35.5	43
78	Packed	16	80x25	640x400	31.5	70
79	Packed	256	80x30	640x480	31.5	60
7C	Packed	256	100x37	800x600	37.5	60
7E	Packed	256	128x48	1024x768	48.5	60
7E I	Packed	256	128x48	1024x768	35.5	43

Note**: I** denotes interlaced display mode.

HIGH REFRESH VIDEO MODES

MODE # (HEX)	DISPLAY MODE	COLOURS	TEXT DISPLAY	PIXEL RES	H FREQ (KHZ)	V FREQ (HZ)
12 *	Planar	16	80x30	640x480	37.5	75
30	8bit linear	256	80x30	640x480	37.5	75
79	Packed	256	80x30	640x480	37.5	75
6A, 70	Planar	16	100x37	800x600	46.9	75
32	8bit linear	256	100x37	800x600	46.9	75
7C	Packed	256	100x37	800x600	46.9	75

FLAT PANEL EXTENDED VIDEO MODES

MODE # (HEX)	DISPLAY MODE	COLOURS	VESA MODE	PIXEL RES	PANEL CLOCK
20	Linear Packed Pixel	16		640x480	25 MHz
22	Linear Packed Pixel	16		800x600	25 MHz
24	Linear Packed Pixel	16		1024x768	25 MHz
28	Linear Packed Pixel	256		1280x1024	25 MHz
30	Linear Packed Pixel	256		640x480	25 MHz
32	Linear Packed Pixel	256		800x600	25 MHz
34	Linear Packed Pixel	256		1024x768	25 MHz
40	Linear Packed Pixel	32K	110	640x480	50 MHz
41	Linear Packed Pixel	64K	111	640x480	50 MHz
50	Linear Packed Pixel	16M	112	640x480	65 MHz
60	Text (8x16)	16		132x25	25 MHz
61	Text (8x8)	16		132x50	25 MHz
6A / 70	Planar	16	102	800x600	25 MHz
72 / 75	Planar	16	104	1024x768	25 MHz
76	Planar	16	106	1280x1024	25 MHz
79	PackPixel	256	101	640x480	25 MHz
7C	PackPixel	256	103	800x600	25 MHz
7E	PackPixel	256	105	1024x768	25 MHz

Note:

1 Flat panels cannot support Interlaced modes. All modes are Non-Interlaced. The default panel size is 640x480.

2 The Flat-panel clock value clock value shown is for a 640x480 DD panel. It may require different clock values for different Flat-panel resolutions.

3 VESA Modes are no-linear modes. (Linear Addressing is disabled).

DIGITAL I/O CONNECTOR

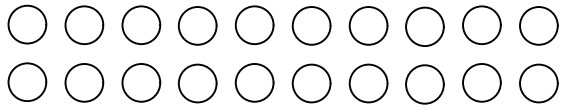
The HAWK PC board provides connectors for 8 bits of HC logic digital I/O and can be located at address 105H. The port provides 8 fixed inputs and 8 fixed outputs. These are NOT configurable I/O ports as in the case of the i8255 digital I/O. An example of how to read and write to the Digital port is provided below. See the appendices for the pin-out details.

To write the 8 bit output port in Qbasic

OUT(&H105), 255: REM set all 8 bits high

To read the 8 bit input port in Qbasic

result = IN(&H105): REM pass all 8 bits of the input port to a variable.



Pin 1, nearest ESS chip

BIOS

The HAWK single board PC uses an AMI System BIOS and an C&T Video BIOS both of which are stored in EPROM. In addition to the System and Video BIOSes, the EPROM also contains the Setup utility, Power-On Self Tests (POST), and the PCI auto-configuration utility. This single board PC supports system BIOS shadowing, allowing the BIOS to execute from 64-bit on-board write-protected DRAM.

The BIOS displays a sign-on message during POST identifying the type of BIOS and a revision code.

SYSTEM SETUP UTILITY

The ROM-based Setup utility allows the configuration to be modified without opening the system for most basic changes. The Setup utility is accessible only during the Power-On Self Test (POST) by pressing the <DEL> key after the POST memory test has started and before boot begins. A prompt may be enabled that informs users to press the <DEL> key to access Setup.

PCI SUPPORT

The AMI BIOS supports Version 2.1 of the PCI BIOS specification. Support is also provided for Version 1.0 of the PCI bridge specification. PCI-to-PCMCIA bridging can also be supported using third party expansion cards.

ISA PLUG AND PLAY

The AMI BIOS incorporates ISA Plug and Play capabilities as defined by the Plug and Play Release 1.0A specification (Plug and Play BIOS Version 1.0A, ESCD Version 1.02). This allows auto-configuration of Plug and Play ISA cards, and resource management for non-Plug and Play (or legacy) ISA cards, when used in conjunction with Plug and Play aware operating systems (such as Windows™ 95).

AUTO-CONFIGURATION CAPABILITIES

The auto-configuration utility operates in conjunction with the system Setup utility to allow the insertion and removal of PCI and ISA Plug and Play cards to the system without user intervention (Plug & Play). When the system is turned on after adding a PCI or ISA Plug and Play card, the BIOS automatically configures interrupts, DMA channels, I/O space, and memory space. The user does not have to configure jumpers or worry about potential resource conflicts. Because PCI and ISA Plug and Play cards use the same interrupt resources as ISA cards, the user can specify the interrupts used by ISA add-in cards in the Setup utility. If using Windows™ 95, the auto-configuration utility only initialises the devices required to boot up, Windows™ 95 initialises all the other devices since it is a Plug and Play aware operating system.

ADVANCED POWER MANAGEMENT

The HAWK AMI BIOS supports power management through System Management Mode (SMM) interrupts to the CPU and Advanced Power Management (APM Version 1.1). In general, power management capabilities will allow the system to be put into a power managed, Stand-by mode either by entering a user configurable hot-key sequence on the keyboard, or by the expiration of a hardware timer which detects system inactivity for a user-configurable time. When in the Stand-by mode, the HAWK single board PC reduces power consumption by using the power saving capabilities of the Pentium processor and also running down hard drives and turning off DPMS compliant monitors. Add-in cards supplied with APM-aware drivers can also be put into a power managed state for further energy savings. The ability to respond to external interrupts is fully maintained while in Stand-by mode, allowing the system to service requests (such as in-coming Fax’s or network messages) while unattended, albeit slowly until the system wakes up.

SLEEP MODE SUPPORT

When Advanced Power Management (APM) is activated in the System BIOS and the Operating System's APM driver is loaded, Sleep mode (Stand-By) can be entered in one of three ways.

Sleep/Resume may be activated by using either a momentary-action sleep switch in the UTILS header, a keyboard hot-key sequence, or by a time-out of the system inactivity timer. Both the keyboard hot-key and the inactivity timer are programmable in the BIOS setup (timer is set to 10 minutes by default). To re-activate the system, or "Resume", the user simply uses the keyboard or mouse, or presses the sleep switch. Note that mouse activity will only "wake up" the system if a mouse driver is loaded. While the system is in Stand-By or "Sleep" mode it is fully capable of responding to, and servicing external interrupts, even though the monitor will only turn on if a user interrupt occurs as mentioned above.

SECURITY FEATURES

SUPERVISOR PASSWORD

If enabled, the supervisor password protects all sensitive Setup options from being changed by a user unless the password is entered (see appendix).

If the password is forgotten, it may be cleared by turning off the system and clearing the CMOS RAM.

USER PASSWORD

The User Password feature provides access to all setup options that do not require the supervisor password. The User Password feature also provides security during the boot process. The User Password can be enabled using the Setup utility. (At boot-up, the system will complete the operating system boot up process, but keyboard and mouse operation will be locked until the User Password is entered. See the Security Menu section of the appendix for more details.)

If the password is forgotten, it can be cleared by turning off the system and clearing the CMOS RAM..

VIDEO BIOS

Both System and Video BIOSes are held in a Flash device. As standard the BIOS shipped will be configured for a 640x480 Dual Scan LCD. If this is not your chosen target panel then you will possibly need to reprogram the Flash Video BIOS with an alternative driver. Please see the supplied Video configuration disk or contact Technical Services at Blue Chip Technology for further details.

CONNECTING AN LCD TO HAWK

Unfortunately, connecting an LCD panel to a PC is not as simple as it is for a CRT. At the time of writing this manual there is still no universally accepted standard interface for LCDs. We strongly recommend that if you in any doubt about connecting a LCD panel to HAWK you contact our Technical Services team *before* you switch on.

For general guidance on the allocation of data bits to the wide variety of panel types please see the following table.

P11 PIN #	SIGNAL	MONO SS 8 BIT	MONO DD 8 BIT	MONO DD 16 BIT	COLOR TFT 9/12/16	COLOR TFT 18/24	COLOR TFT HR 18/24	COLOR STN SS 8 BIT	COLOR STN SS 16 BIT	COLOR STN DD 8 BIT	COLOR STN DD 16 BIT
19	Data 0		UD3	UD7	B0	B0	B00	R1…	R1…	UR1…	UR0…
21	Data 1		UD2	UD6	B1	B1	B01	B1…	G1…	UG1…	UG0…
23	Data 2		UD1	UD5	B2	B2	B02	G2…	B1…	UB1…	UB0…
25	Data 3		UD0	UD4	B3	B3	B03	R3…	R2…	UR2…	UR1…
27	Data 4		LD3	UD3	B4	B4	B10	B3…	G2…	LR1…	LR0…
29	Data 5		LD2	UD2	G0	B5	B11	G4…	B2…	LG1…	LG0…
31	Data 6		LD1	UD1	G1	B6	B12	R5…	R3…	LB1…	LB0…
33	Data 7		LD0	UD0	G2	B7	B13	B5…	G3…	LR2…	LR1…
35	Data 8	P0		LD7	G3	G0	G00	SHCLKU	B3…		UG1…
37	Data 9	P1		LD6	G4	G1	G01		R4…		UB1…
39	Data 10	P2		LD5	G5	G2	G02		G4…		UR2…
41	Data 11	P3		LD4	R0	G3	G03		B4…		UG2…
43	Data 12	P4		LD3	R1	G4	G10		R5…		LG1…
45	Data 13	P5		LD2	R2	G5	G11		G5…		LB1…
47	Data 14	P6		LD1	R3	G6	G12		B5…		LR2…
49	Data 15	P7		LD0	R4	G7	G13		R6…		LG2…
50	Data 16					R0	R00				
46	Data 17					R1	R01				
42	Data 18					R2	R02				
38	Data 19					R3	R03				
34	Data 20					R4	R10				
30	Data 21					R5	R11				
26	Data 22					R6	R12				
22	Data 23					R7	R13				
11	SHFCLK	SHFCLK	SHFCLK	SHFCLK	SHFCLK	SHFCLK	SHFCLK	SHFCLKL	SHFCLK	SHFCLK	SHFCLK

In addition the following signals may need connecting to the target LCD panel:

P11 PIN #	SIGNAL	DESCRIPTION
1	5/3V3	CRT 10 (AS SET BY J15)
2	VSYNC	CRT Vertical Sync
3	Switched +12 volts	Power sequenced +12 volts
6	HSYNC	CRT Horizontal Sync
7, 9	Switched +5 volts	Power sequenced +5 volts
10	General purpose 1	
13	LCLK	
14	General purpose 2	
15	MOD	Configured as BLANK# or Display Enable for TFT displays
17	FLM	First Line Marker - LCD equivalent of VSYNC

Always ensure maximum ground connections to the target LCD panel especially as the clock frequencies rise. P11 pins 4, 8, 12, 16, 18, 20, 24, 28, 32, 36, 40, 44, and 48 are provided as ground pins.

CONNECTORS

A selection of connectors is incorporated on the HAWK PC board. These provide connectivity to standard external peripherals (monitor, keyboard, etc.), in-chassis peripherals (disk drives, etc.), and bus devices. A complete table of the available connectors and their pin-outs is given in the appendices. The PC board layout at the end of the manual shows their positions.

BACK PANEL CONNECTORS

The back panel provides external access to the CRT, Parallel printer, PS/2 mouse, keyboard, Serial 1 & 2, Ethernet, and dual USB ports. All the connectors follow the industry standard. The diagram shows the general location of the connectors.

ON-BOARD CONNECTORS

There are connectors on-board for Floppy Disk Drive, IDE, LCD, Digital I/O, Serials 3 & 4, RS422/485, PC/104, ISA, Sound, CD Audio, Supervisory micro and utilities connector. There are also sockets for SIMMs, COAST (cache), Flash & SRAM Solid State Disks and external battery.

In addition, connectors provide for:

- Power supply connection
- On-board programming of the EPLD. This is for manufacture only, and is not a user connection.

UTILITY CONNECTOR

The HAWK PC board provides connectors to support functions which would normally be located within the enclosure, and also duplicate connections for some of the external interfaces (System Speaker, System Reset Switch, Keyboard, Power LED Hard Drive Activity LED, and an External Battery).

SPEAKER

No on-board Piezo speaker is provided. An off-board speaker may be connected to the header (P16 pins 1 & 2). The speaker provides error beep code information during the Power-On Self Test if the system cannot use the video interface.

RESET

Two pins of header P16 (pins 3 & 4) may be connected to a momentary normally open SPST switch. When the switch is closed, the system will perform a hard reset and run the POST.

IDE LED

Two pins of header P16 (pins 13 & 14) may be connected to an LED to provide a light when an IDE hard drive connected to the on-board IDE controller is active.

BUS CONNECTORS

The board incorporates the standard PC/AT 16-bit ISA and PC/104 bus connectors for expansion. See the appendices for the pin-out details.

JUMPERS

Jumpers are used on the board to select various options. Some of the jumpers are factory set to suit particular semiconductor options. These must not be disturbed, or damage to the board may ensue. Refer to the board layout drawing at the end of the manual for the positions of the various jumpers.

CPU FREQUENCY SELECTION J4 & J5

The external CPU bus operates at frequencies of 50, 60 and 66 MHz but is scaled up internally giving a range of CPU frequencies of 75 to 166 MHz. There are four links (in two locations) involved in CPU frequency selection: **J4** and **J5**. Link **J4** selects the host CPU operating frequency of 50, 60 and 66 MHz. Link **J5** selects the clock scaling (multiplying) factor.

Link J5 is latched by the CPU on reset and used to configure the CPU phase locked loop oscillator. This allows higher speed processors to be clocked down (e.g. running a P133 as a P100), but over clocking processors is not recommended as it will degrade the reliability of the device over time. Note also that there are internal differences between each of the CPU types, i.e. there are register differences between a P100 and a P133, it is not simply silicon grading as was the case for 486 type CPUs.

INTERNAL CPU CLOCK SPEED J5

These jumpers sets the internal CPU clock speed to either 1½, 2, 2½, 3 or 3 ½ times that of the external CPU clock speed. These jumpers should be configured depending on the speed of the processor.

CPU CLOCK MULTIPLIER	PAIR A	PAIR B
1.5 x / 3 .5 x	Open	Open
2 x	Open	Link
2.5 x	Link	Link
3 x	Link	Open

CPU I/O VOLTAGE SELECT J3 (3 LINKS)

This jumper selects between Classic Pentium Processors and MMX Pentium Processors. **Note** care must be taken to ensure the correct CPU core voltage is selected when using MMX CPU's, this can be changed via the jumper links J2. Most MMX CPU's have an CPU core Voltage of 2.9V

CPU I/O VOLTAGE.	STD	VRT
MMX CPU	Open	Link
Classic CPU	Link	Open

EXTERNAL CPU CLOCK SPEED J4

This jumper block sets the CPU's external operating frequency to memory at 50, 60, or 66 MHz. The default setting depends on the specific memory and type of Pentium processor installed. It is used in conjunction with J5.

EXTERNAL BUS FREQ.	PAIR A	PAIR B
50 MHz	Link	Link
60 MHz	Link	Open
66 MHz	Open	Link
Reserved	Open	Open

SUMMARY OF LINK SETTINGS FOR CLASSIC PENTIUM CPU'S

CPU CORE SPEED (MHZ)	HOST BUS SPEED (MHZ)	PCI BUS SPEED (MHZ)	HOST CLK SCALING FACTOR	J5 A	J5 B	J4 A	J4 B
75	50	25	1.5	Open	Open	Link	Link
90	60	30	1.5	Open	Open	Link	Open
100	66	33	1.5	Open	Open	Open	Link
120	60	30	2	Open	Link	Link	Open
133	66	33	2	Open	Link	Open	Link
150	60	30	2.5	Link	Link	Link	Open
166	66	33	2.5	Link	Link	Open	Link
200	66	33	3	Link	Open	Open	Link

MMX PROCESSORS

The Hawk is capable of supporting MMX CPU's up to P233.
To correctly support MMX CPU's J3 (3 links) must be moved to the VRT setting as shown in the table of Jumpers.
Below is a table of jumper link settings of all supported MMX CPU's

SUMMARY OF LINK SETTINGS FOR MMX PENTIUMS CPU'S

CPU CORE SPEED (MHZ)	HOST BUS SPEED (MHZ)	PCI BUS SPEED (MHZ)	HOST CLK SCALING FACTOR	J5 A	J5 B	J4 A	J4 B
133	66	33	2	Open	Link	Open	Link
166	66	33	2.5	Link	Link	Open	Link
200	66	33	3	Link	Open	Open	Link
233	66	33	3.5	Open	Open	Open	Link

ON-BOARD VIDEO J6

The HAWK is equipped with a link (**J6**) to allow the user to disable the on-board video when external video adapters are being used. If a PCI video adapter is fitted into a system, the on-board video will be automatically disabled without having to fit a jumper on J6.

J6 must be fitted when using ISA based VGA adapter boards in a HAWK based system.

CMOS BATTERY SOURCE (CLEAR CMOS) J1

This jumper is used to clear the CMOS RAM in the event that the contents become corrupt. It selects the source of backup power to the CMOS RAM, and also allows the CMOS to be cleared down to the default settings.

Fitting the link to the "CLR" position with the power off, allows on-board capacitors to discharge and will reset the CMOS memory. The jumper should then be returned to the "NORM" position to restore normal operation.

TABLE OF JUMPERS

JUMPER	AREA OF INFLUENCE	LINK	ACTION
J1	CMOS Battery Support	None CLR NORM	Not Allowed Clear CMOS RAM Use on-board battery
J2	CPU Core Voltage Select	None 2.9 3.3 3.45 3.6	Not Allowed 2V9 CPU core 3V3 CPU core 3V45 CPU core 3V6 CPU core
J3	CPU I/O Voltage Select (3 links)	VRT STD	VRT CPU (MMX) Standard CPU
J4	Select External Bus Frequency. Use in conjunction with J5	A B L L L O O L O O	External Bus Frequency 50 MHz 60 MHz 66 MHz Reserved
J5	Selects the internal CPU clock speed. Use in conjunction with J4	A B O O O L L L L O	(External CPU speed) x 1.5 / x 3.5 x 2 x 2.5 x 3
J6	On-board video select	None Link	Enabled Disabled
J7	Serial Port 2 mode selection	None Link	RS485 Full Duplex selected RS485 Half Duplex selected
J8	Serial Port 2 pin 9 selection	5 12 24 RI	+5 volts fed to pin 9 of D type +12 volts fed to pin 9 of D type +24 volts fed to pin 9 of D type * Ringing Indicator fed to pin 9 of D type
J9	Serial Port 1 pin 9 selection	5 12 24 RI	+5 volts fed to pin 9 of D type +12 volts fed to pin 9 of D type +24 volts fed to pin 9 of D type * Ringing Indicator fed to pin 9 of D type
J10	Serial Port 3 pin 9 selection	5 12 24 RI	+5 volts fed to pin 9 of D type +12 volts fed to pin 9 of D type +24 volts fed to pin 9 of D type * Ringing Indicator fed to pin 9 of D type
J11	Serial Port 2 mode of operation	232 FUL HLF	RS232 selected RS422/485 Full duplex selected RS485 Half duplex selected

J12	Serial Port 4 pin 9 selection	5 12 24 RI	+5 volts fed to pin 9 of D type +12 volts fed to pin 9 of D type +24 volts fed to pin 9 of D type * Ringing Indicator fed to pin 9 of D type
J13	VEE output voltage polarity	1-2 2-3	-ve voltage +ve voltage
J14	VEE Control Voltage		Connect a 50K potentiometer with the wiper on pin 2 to vary voltage between 8 and 50 volts
J15	5V/3V3 Panel Voltage	3V3 5V	Fitted for 3V LCD panels Fitted for 5V LCD panels

In the table “L” indicates the presence of a link, “O” the absence.

STATUS LEDS

Along the top edge of the PCB on the reverse side is a row of LEDs. These are arranged in groups to indicate the status of various board functions:

P.O.S.T. DISPLAY

Red LEDs LSB to MSB inclusive display the Power On Self Test (POST) data byte. The LED is illuminated when the POST data bit is 1. See the Appendix for details of the error codes.

POWER SUPPLY INDICATORS

Five green LEDs marked +3, +5, +12, -12 & -5 adjacent to the power connector show the presence of the power supplies. Each LED is illuminated when the appropriate voltage is present.

IDE ACTIVITY DISPLAY

The Yellow LED marked SL indicates primary IDE activity (Hard disk or CD-ROM) and is illuminated when active.

SYSTEM RESET STATUS

The Red LED marked RST indicates the system reset status. The LED is illuminated when in held in reset.

MONITOR MICROCONTROLLER STATUS

The Yellow LED marked MF indicates the status of the monitor microcontroller (if fitted). The LED is illuminated when a fault condition has occurred.

WATCHDOG TIMER STATUS

The Yellow LED marked WD indicates the watchdog time out status. The LED is illuminated when a timeout has occurred.

USER-INSTALLABLE UPGRADES

SYSTEM MEMORY

The table shows the possible memory combinations. HAWK will support both Fast Page DRAM or EDO DRAM SIMMs, but they cannot be mixed within the same memory bank. Parity generation and detection are supported, and Error Correction can be invoked when using parity SIMMs (x36). See BIOS Setup options.

SIMM requirements are 70ns Fast Page Mode or 60nS EDO DRAM (70 ns EDO may be used with a 60 MHz or slower external CPU clock) with tin-lead connectors.

SIMM 1,2 (BANK A) SIMM TYPE (AMOUNT)	TOTAL SYSTEM MEMORY
1M X 32 (4 MB)	8 MB
2M X 32 (8 MB)	16 MB
4M X 32 (16 MB)	32 MB
8M X 32 (32 MB)	64 MB
16M x 32 (64 MB)	128 MB
64M X 32 (128 MB)	256 MB

It is recommended that a quality supply of SIMM modules with be used to improve the performance and reliability. It is also recommended that tin plated SIMM modules be used with tin SIMM racks for added reliability. Please contact Blue Chip Technology for a recommended supply of Memory SIMM modules.

Note: SIMMs may be parity (x 36) or non-parity (x 32)

EDO DRAM

Extended Data Out (or Hyper Page) DRAM is designed to improve the DRAM read performance. EDO DRAM holds the memory data valid until the next CAS# falling edge, unlike standard fast page mode DRAM which tri-states the memory data when CAS# negates to precharge for the next cycle. With EDO, the CAS# precharge overlaps the data valid time, allowing CAS# to negate earlier while still satisfying the memory data valid window time.

REAL TIME CLOCK BATTERY REPLACEMENT

The on-board battery may be replaced using a Varta CR2032 Li-Mn 3 volt button cell, or equivalent.

CPU UPGRADE

A SPGA socket provides users with a performance upgrade path to the Pentium Overdrive Processors.

GRAPHICS MEMORY UPGRADE

The HAWK single board PC has 1 MB of Fast Page DRAM installed for graphics. No expansion is available.

SOFTWARE DESCRIPTION

BIOS SETUP - PROVISIONAL

This section details the BIOS CMOS Setup Utility. The parameters described below are based on BIOS version 1.00; other BIOS versions may differ from the description below as new features are added.

OVERVIEW OF THE SETUP MENU SCREENS

The Setup program initially displays the Main menu screen. In each screen there are options for modifying the system configuration. Select a sub-menu screen by pressing the up <↑> or down <↓> arrow keys, followed by <Enter>. Within the menu use the up <↑> or down <↓> keys to select an item, then use <PgUp> or <PgDn> to modify it. For certain items, pressing <Enter> will bring up a subscreen. After you have selected an item, use the <PgUp> or <PgDn> keys to modify the setting.

MAIN SCREEN

Shows the following menu:

Standard Setup
Advanced CMOS Setup
Advanced Chipset Setup
Power Management Setup
PCI / PnP Setup
Peripheral Setup
Auto Detect Hard Disk
Change User Password
Change Supervisor Password
Auto Configuration with Optimal Settings
Auto Configuration with Fail Safe Settings
Save Settings and Exit
Exit without Saving

Their operation is as follows:

STANDARD SETUP

For setting up and modifying basic items such as floppy disk drives, hard drives, and system time & date.

ADVANCED CMOS SETUP

For modifying the more advanced features of the PC (e.g. system bootup options).

ADVANCED CHIPSET SETUP

For modifying hardware level options.

POWER MANAGEMENT SETUP

For specifying the “Green PC” features such as IDE and VGA timeouts.

PCI / PNP SETUP

For specifying Plug and Play options (e.g. IRQ assignments).

PERIPHERAL SETUP

For specifying the system peripheral options such as serial and parallel port modes.

AUTO DETECT HARD DISK

Automatically determines the parameters of any IDE devices connected, and sets up the parameters for “USER DEFINED” drives.

CHANGE USER PASSWORD

Allows the password for the user level options to be set or changed. This option cannot be changed unless a supervisor password has been set.

CHANGE SUPERVISOR PASSWORD

Allows the password for the supervisor level options to be changed.

AUTO CONFIGURATION WITH OPTIMAL SETTINGS

Resets the CMOS setup options to a high performance configuration. The optimal default settings are best case values and should optimise the system performance. If CMOS RAM is corrupted, the optimal settings are loaded automatically.

AUTO CONFIGURATION WITH FAIL SAFE SETTINGS

Resets the CMOS setup options to a lower performance but guaranteed working configuration. The fail safe settings provide far from optimal system performance, but are the most stable settings. Use these settings as an diagnostics aid if the system is performing erratically.

SAVE SETTINGS AND EXIT

When selected, this allows you to save the change to CMOS and exit the Setup program. You can also press the <F10> key anywhere in the Setup program to do this.

EXIT WITHOUT SAVING

When selected, this allows you to exit the Setup program without saving any changes. This means that any changes made while in the Setup program will be discarded and **NOT SAVED**. Pressing the <Esc> key in any of the four main screens will do this.

OVERVIEW OF THE SETUP KEYS

SETUP KEY	DESCRIPTION
<F1>	Pressing the <F1> key brings up a help screen for the currently selected item.
<Esc>	Pressing the <Esc> key takes you back to the previous screen. Pressing it in the Main, Advanced, Security, or Exit screen allows you to Exit Discarding Changes (see later in this chapter).
<PgUp> <PgDn>	Pressing either key moves the selection of the current item up or down the available options.
<↑>	Pressing the up <↑> key changes the selection to the previous item or option.
<↓>	Pressing the down <↓> key changes the selection the to the next item or option.
<←> <→>	Pressing the left <←> or right <→> keys in the Main, Advanced, Security, or Exit menu screens changes the menu screen. Pressing either key in a subscreen does nothing.
<F5>	Pressing the <F5> key allows you to Load Setup Defaults (see later in this chapter).
<F6>	Pressing the <F6> key allows you to Discard Changes (see later in this chapter).
<F10>	Pressing the <F10> key allows you to Exit Saving Changes (see later in this chapter).

STANDARD SETUP

This section describes the Setup options found on the standard setup screen.

SYSTEM DATE

When selected, this allows you to set the current date by specifying a date, month and year.

SYSTEM TIME

When selected, this allows you to set the current time by entering values for hours, minutes and seconds..

FLOPPY A: TYPE

When selected, this allows you to cycle through the available options to specify the physical size and capacity of the diskette drive. The options are Disabled; 360 KB, 5.25-inch; 1.2 MB, 5.25-inch; 720 KB, 3.5-inch; 1.44/1.25 MB, 3.5-inch; 2.88 MB, 3.5-inch. The default is 1.44 MB, 3.5-inch.

FLOPPY B: TYPE

When selected, this allows you to cycle through the available options to specify the physical size and capacity of the diskette drive. The options are Disabled, 360 KB, 5.25-inch; 1.2 MB, 5.25-inch; 720 KB, 3.5-inch; 1.44/1.25 MB, 3.5-inch; 2.88 MB, 3.5-inch. The default is Disabled.

PRIMARY IDE MASTER

This reports if a primary master IDE hard disk is connected to the system and allows for the configuration of drive parameters.

When selected, this allows the manual configuration of the hard drive or have the system auto configure it. The options are Auto Configured, User Definable and Disabled. There are also options for IDE CD-ROM and 46 predefined hard drive types. If you select User Definable then the Number of Cylinders, Number of Heads, and Number of Sectors can each be modified. The default for this is “Auto”.

PRIMARY IDE SLAVE

This reports if a primary slave IDE hard disk is connected to the system. It is configured exactly as described under Primary IDE Master above. The default is “Not Installed”.

SECONDARY IDE MASTER

This reports if a secondary master IDE hard disk is connected to the system. It is configured exactly as described under Primary IDE Master above. The default is “Not Installed”.

SECONDARY IDE SLAVE

This reports if a secondary slave IDE hard disk is connected to the system. It is configured exactly as described under Primary IDE Master above. The default is “Not Installed”.

NUMBER OF CYLINDERS

If Hard Disk Type is set to User Definable, you must type the correct number of cylinders for your hard disk. If Hard Disk Type is set to Auto Configured, this reports the number of cylinders for your hard disk and cannot be modified.

NUMBER OF HEADS

If Hard Disk Type is set to User Definable, you must type the correct number of heads for your hard disk. If Hard Disk Type is set to Auto Configured, this reports the number of heads for your hard disk and cannot be modified.

NUMBER OF SECTORS

If Hard Disk Type is set to User Definable, you must type the correct number of sectors for your hard disk. If Hard Disk Type is set to Auto Configured, this reports the number of sectors for your hard disk and cannot be modified.

ADVANCED SYSTEM SETUP

QUICK BOOT

Set this option to "Enabled " to instruct the BIOS to boot quickly.

If set to "Enabled" the BIOS does not test memory above 1 MB and the BIOS does not wait up to 40 seconds for a READY signal from the hard drive. If the READY signal is not received immediately from the IDE drive, it is not configured (as if it was absent). The default is "Disabled".

BOOTUP SEQUENCE

This option specifies the sequence of the boot drives. The options are:

1st Boot Device

2nd Boot Device

3rd Boot Device

Each of these options can be set to boot from the following list of peripherals.

Disabled - On selection HAWK no boot device will be sought.

IDE-0 - On selection HAWK will attempt to boot from the attached first physical (E-) IDE drive.

IDE-1 - On selection HAWK will attempt to boot from the attached second physical (E-) IDE drive.

IDE-2 - On selection HAWK will attempt to boot from the attached third physical (E-) IDE drive.

IDE-3 - On selection HAWK will attempt to boot from the attached fourth physical (E-) IDE drive.

Floppy - On selection HAWK will attempt to boot from the attached floppy drive. Capacities from 360KB to 2.88MB are supported.

Floptical - On selection HAWK will attempt to boot from the attached LS120 optical drive

CDROM - On selection HAWK will attempt to boot from the attached IDE CDROM drive.

SCSI - On selection HAWK will attempt to boot from the SCSI Boot ROM fitted on your host SCSI adapter.

Network - On selection HAWK will boot from the on-board Ethernet Boot ROM, where fitted.

The default setting is:

1st Boot Device - Floppy

2nd Boot Device - IDE-0

3rd Boot Device - Disabled

S.M.A.R.T HARD DRIVES

This option allows the selection of SMART drive technology for the attached hard disks. The Options are Enabled or Disabled. The default is 'Disabled'.

BOOT CPU SPEED

Allows the system's boot speed to be set. The options are "Low" and "High". The optimal setting is "High", the fail-safe is "Low". If High is selected, boot-up occurs at full speed. If Low is selected, the board operates at a slower speed (approximately equivalent to 25 MHz PC-AT).

BOOT UP NUM LOCK

Allows you to set the start up state of "Num Lock" on your keyboard. The options are "On" and "Off". The default is On.

FLOPPY DRIVE SWAP

Set this option to "Enabled" to permit the BIOS to swap drives A: and B:. The available options are "Enabled" and "Disabled". The default setting is disabled.

FLOPPY DRIVE SEEK

Set this option to specify floppy drive A: will perform a seek operation on system boot. are “Enabled” and “Disabled”. The default setting is disabled.

MOUSE SUPPORT

When this option is enabled the BIOS will support a PS/2 style mouse. The options are “Enabled” and “Disabled”. The default setting is enabled.

SYSTEM KEYBOARD

This option specifies that a keyboard is attached to the computer. The settings are Present or Absent. The Optimal and Fail-Safe default settings are Present.

PRIMARY DISPLAY

This option specifies the type of display monitor and adapter in the computer. The settings are Mono, CGA40, CGA80, EGA/VGA, or Absent. The Optimal and Fail-Safe default settings are EGA/VGA.

PASSWORD CHECK

This option enables password checking every time the computer is powered on or every time Setup is executed. If Always is chosen, a user password prompt appears every time the computer is turned on. If Setup is chosen, the password prompt appears if Setup is executed.

BOOT TO OS/2

Set this option to Yes to permit AMIBIOS to run with IBM OS/2. The settings are Yes or No. The default setting is No.

WAIT FOR F1 IF ERROR

AMIBIOS POST error messages are followed by:

Press <F1> to continue

If this option is set to Disabled, AMIBIOS does not wait for you to press the <F1> key after an error message. The settings are Disabled or Enabled. The Optimal and Fail-Safe default settings are Enabled.

HIT DEL MESSAGE DISPLAY

Set this option to Disabled to prevent

Hit <DEL> if you want to run Setup

from appearing on the first AMIBIOS screen when the computer boots. The settings are Disabled or Enabled. The Optimal and Fail-Safe default settings are Enabled.

INTERNAL CACHE

This option specifies the caching algorithm used for L1 internal cache memory. The settings are :

SETTING	DESCRIPTION
Disabled	Neither L1 internal cache memory on the CPU or L2 secondary cache memory is disabled
WriteBack (default)	Use the write-back caching algorithm
WriteThru	Use the write through caching algorithm

EXTERNAL CACHE

This option specifies the caching algorithm used for L2 secondary (external) cache memory. The settings are :

SETTING	DESCRIPTION
Disabled	L2 cache is disabled
WriteBack	L2 cache is write back.
WriteThru	L2 cache is write through

SYSTEM BIOS SHADOW CACHEABLE

When this option is set to Enabled, the contents of the F0000h system memory segment can be read from or written to L2 secondary cache memory. The contents of the F0000h memory segment are always copied from the BIOS ROM to system RAM for faster execution.

The settings are Enabled or Disabled. The Optimal default setting is Enabled. The Fail-Safe default is Disabled. Default is Enabled.

C000, 16K Shadow
C400, 16K Shadow
C800, 16K Shadow
CC00, 16K Shadow
D000, 16K Shadow
D400, 16K Shadow
D800, 16K Shadow
DC00, 16K Shadow

These options control the location of the contents of the 16KB blocks of ROM beginning at the specified memory location. If no adapter ROM is using the named ROM area, this area is made available to the local bus. The settings are :

SETTING	DESCRIPTION
Enabled	The contents of C0000h - C3FFFh are written to the same address in system memory (RAM) for faster execution.
Cache	The contents of the named ROM area are written to the same address in system memory (RAM) for faster execution, if an adapter ROM will be using the named ROM area. Also, the contents of the RAM area can be read from and written to cache memory.
Disabled	The video ROM is not copied to RAM. The contents of the video ROM cannot be read from or written to cache memory.

The default setting is Cache for C000 and C400; disabled for the remainder.

In the AMIBIOS for the Intel Triton chipset, the E000h page is used as ROM during POST, but shadowing is disabled and the ROM CS# signal is disabled to make the E000h page available on the local bus.

ADVANCED CHIPSET SETUP

USB FUNCTION

This option controls the operation of the USB ports on HAWK. The options are Enabled or Disabled. The default is 'Enabled', the fail-safe default is 'Disabled'.

USB KEYBOARD/MOUSE LEGACY SUPPORT

This option allows the Triton chipset to emulate a standard 8042 interface for the keyboard and mouse functions when the operating environment does not support the USB keyboard and mouse functions directly. The settings are Enabled and Disabled. The default is 'Enabled'.

USB PASSIVE RELEASE ENABLE

This option controls the USB passive release function on HAWK. The settings are Enabled or Disabled. The default and fail-safe settings are 'Enabled'.

GLOBAL TRITON 2 ENABLE

This option controls the enhanced functions of the Intel Triton II chipset. The settings are Enabled or Disabled. The default and fail-safe settings are 'Enabled'.

MEMORY HOLE

Use this option to specify an area in memory that cannot be addressed on the ISA bus. The settings are Disabled, 512-640K or 15-16MB. The default setting is 'Disabled'.

DRAM TIMINGS

Specify the RAS access speed of the SIMMs installed in HAWK as system memory. The settings are 60nS, 70nS and Manual. The default is 70nS.

Caution

If you have installed SIMMs with different speeds in HAWK, select the speed of the slowest SIMM. You must always use SIMMs that have the same speed.

IRQ12/M MOUSE FUNCTION

Set this option to Enabled to specify that IRQ12 will be used for the mouse. The settings are Disabled or Enabled. The Optimal and Fail-Safe default settings are Enabled.

8-BIT I/O RECOVERY TIME (SYSCLK)

This option specifies the length of the delay (in units of SYSCLKs) inserted between consecutive 8-bit I/O operations. The settings are 1,2,3,4,5,6,7, or 8. the Optimal and Fail-Safe default settings are 8.

16-BIT I/O RECOVERY TIME (SYSCLK)

This option specifies the length of the delay (in SYSCLKs) inserted between consecutive 16-bit I/O operations. The settings are 1,2,3,4,5,6,7 or 8. The Optimal and Fail-Safe default settings are 4.

POWER MANAGEMENT SETUP

POWER MANAGEMENT / APM

Set this option to Enabled to enable the power management and APM (advanced Power Management) features.

The settings are Enabled, Disabled or Inst-On. The default settings are Disabled.

INSTANT ON SUPPORT

If this option is set in Power Management / APM it allows the computer to go to full power on mode when leaving a power-conserving state. AMIBIOS uses the RTC Alarm function to wake the computer at a pre-specified time. The settings are 1 to 14 minutes, or Disabled. The default settings are Disabled.

GREEN PC MONITOR POWER STATE

This option specifies the power management state that the Green PC-compliant video monitor enters after the specified period of display inactivity has expired. The settings are, Off, Standby, or Suspend. The default settings are Standby.

VIDEO POWER DOWN MODE

This option specifies the power management state that the video subsystem enters after the specified period of display inactivity has expired. The settings are Disabled, Standby or Suspend. The default settings are Disabled.

HARD DISK POWER DOWN MODE

This option specifies the power management state that the hard disk drive enters after the specified period of display inactivity has expired. The settings are Disabled, Standby, or Suspend. The default settings are Disabled.

HARD DISK TIMEOUT (MIN)

This option specifies the length of a period of hard disk inactivity. When this period expires, the hard disk drive enters the power-conserving mode specified in the Hard Disk Power Down Mode option described above. The settings are Disabled, 1 Min (minutes), and all one minute intervals up to and including 15 Min. The default settings are Disabled.

STANDBY TIMEOUT

This option specifies the length of the period of system inactivity when the computer is in Full-On mode before the computer is placed in Standby mode. In Standby mode, some power use is curtailed. The settings are Disabled, 1 Min, 2 Min and all one minute intervals up to and including 15 Min. The default settings are Disabled.

SUSPEND TIMEOUT

This option specifies the length of the period of system inactivity when the computer is already in Standby mode before the computer is placed in Suspend mode. In Suspend mode, nearly all power use is curtailed. The settings are Disabled, 1 Min, 2 Min, and all one minute intervals up to and including 15 Min. The default settings are Disabled.

SLOW CLOCK RATIO

This option specifies the speed at which the system clock runs in power saving modes. The settings are expressed as a ratio between the normal clock speed and the power down clock speed. The settings are 1:1, 1:2 (half as fast as normal), 1:4 ((the normal clock speed), 1:8, 1:16, 1:32, 1:64, or 1:128. The default setting is 1:8.

DISPLAY ACTIVITY

This option specifies if AMIBIOS is to monitor activity on the display monitor for power conservation purposes. When this option is set to Monitor and there is no display activity for the length of time specified in the value in the Full-On to Standby Timeout (Min) option, the computer enters a power saving state. The settings are Monitor or Ignore. The default settings are Ignore.

IRQ 3, 4, 5, 7, 9, 10, 11, 12, 13, 14, 15

These options enable event monitoring. When the computer is in a power saving mode, activity on the named interrupt request line is monitored by AMIBIOS. When any activity occurs, the computer enters Full On mode.

Each of these options can be set to Monitor or Ignore. The provisional settings are:

	OPTIMAL	FAIL-SAFE
IRQ 3	Monitor	Ignore
IRQ 4	Monitor	Ignore
IRQ 5	Ignore	Ignore
IRQ 7	Monitor	Ignore
IRQ 9	Ignore	Ignore
IRQ 10	Ignore	Ignore
IRQ 11	Ignore	Ignore
IRQ 12	Monitor	Ignore
IRQ 13	Ignore	Ignore
IRQ 14	Monitor	Ignore
IRQ 15	Monitor	Ignore

PCI / PNP SETUP

PLUG AND PLAY AWARE OS

Set this option to Yes if the operating system installed in the computer is Plug and Play-aware. AMIBIOS only detects and enables PnP ISA adapter cards that are required for system boot. The Windows 95 operating system detects and enables all other PnP-aware adapter cards. Windows 95 is PnP-aware. Set this option to No if the operating system (such as DOS, OS/2, Windows 3.x) does not use PnP. You must set this option correctly or PnP-aware adapter cards installed in your computer will not be configured properly. The settings are No or Yes. The Optimal and Fail-Safe default settings are No.

PCI LATENCY TIMER (IN PCI CLOCKS)

This option sets latency of all PCI devices on the PCI bus. The settings are in units equal to PCI clocks. The settings are 32, 64, 96, 128, 160, 192, 224, or 248. The Optimal and Fail-Safe default settings are 64.

PCI VGA PALETTE SNOOP

This option must be set to Enabled if any ISA adapter card installed in the computer requires VGA palette snooping. The settings are Disabled or Enabled. The Optimal and Fail-Safe default settings are Disabled.

PCI IDE BUS/MASTER

Set this option to Enabled to specify that the IDE controller on the PCI local bus has bus mastering capability. The settings are Disabled or Enabled. The Optimal and Fail-Safe default settings are Disabled.

OFFBOARD PCI IDE CARD

This option specifies if an offboard PCI IDE controller adapter card is used in the computer. You must also specify the PCI expansion slot on HAWK where the offboard PCI IDE controller card is installed. If an offboard PCI IDE controller is used, the on-board IDE controller on HAWK is automatically disabled. The settings are Disabled, Auto, Slot1, Slot2, Slot3, or Slot 4.

If Auto is selected, AMIBIOS automatically determines the correct setting for this option. The Optimal and Fail-Safe default settings are Auto.

In the AMIBIOS for the Intel Triton chipset, this option forces IRQ 14 and 15 to a PCI slot on the PCI local bus. This is necessary to support non-compliant PCI IDE adapter cards.

OFFBOARD PCI IDE PRIMARY IRQ

This option specifies the PCI interrupt used by the primary IDE channel on the offboard PCI IDE controller. The settings are Disabled, INTA, INTB, INTC, INTD or Hardwired. The Optimal and Fail-Safe default settings are Disabled.

OFFBOARD PCI IDE SECONDARY IRQ

This option specifies the PCI interrupt used by the secondary IDE channel on the offboard PCI IDE controller. The settings are Disabled, INTA, INTB, INTC, INTD or Hardwired. The Optimal and Fail-Safe default settings are Disabled.

DMA CHANNELS 0, 1, 3, 5, 6, 7

These options specify the bus to which the DMA channel is allocated.

These options determine if AMIBIOS should remove a DMA channel from the available pool passed to BIOS configurable devices. The available pool is determined by reading the ESCD NVRAM. If more DMA channels must be removed from the pool, the end user can use these PCI/PnP Setup options to remove the channel by assigning the option to the ISA/EISA setting. Onboard I/O is configurable by AMIBIOS. The DMA channels used by onboard I/O are configured as PCI/PnP.

The provisional default settings are:

	OPTIMAL	FAILSAFE
Channel 0	PnP	PnP
Channel 1	PnP	PnP
Channel 3	ISA/EISA	ISA/EISA
Channel 5	PnP	PnP
Channel 6	PnP	PnP
Channel 7	PnP	PnP

IRQ 3, 4, 5, 7, 9, 10, 11, 14, 15

These options specify the bus that the named interrupt request lines (IRQs) are used on. These options allow you to specify IRQs for use by legacy ISA adapter cards.

These options determine if AMIBIOS should remove an IRQ from the pool of available IRQs passed to BIOS configurable devices. The available IRQ pool is determined by reading the ESCD NVRAM. If more IRQs must be removed from the pool, the end user can use these PCI/PnP Setup options to remove the IRQ by assigning the option to the ISA/EISA setting. Onboard I/O is configurable by AMIBIOS. The IRQs used by onboard I/O are configured as PCI/PnP.

The provisional optimal and fail-safe settings are:

	OPTIMAL	FAILSAFE
IRQ 3	ISA/EISA	ISA/EISA
IRQ 4	ISA/EISA	ISA/EISA
IRQ 5	PnP	PnP
IRQ 7	ISA/EISA	ISA/EISA
IRQ 9	PnP	PnP
IRQ 10	PnP	PnP
IRQ 11	PnP	PnP
IRQ 14	PnP	PnP
IRQ 15	PnP	PnP

RESERVED MEMORY SIZE

This option specifies the size of the memory area reserved for legacy ISA adapter cards.

The settings are Disabled, 16K, 32K, or 64K. The Optimal and Fail-Safe default settings are Disabled.

RESERVED MEMORY ADDRESS

This option specifies the beginning address (in hex) of the reserved memory area. The specified ROM memory area is reserved for use by legacy ISA adapter cards.

The settings are C0000, C4000, C8000, CC000, D0000, D4000, D8000, DC000. The Optimal and Fail-Safe default settings are C8000.

PERIPHERAL SETUP

Peripheral Setup options are displayed by choosing the Peripheral Setup icon from the WINBIOS Setup main menu. All Peripheral Setup options are described in this section.

ONBOARD PCI IDE

This option specifies the onboard IDE controller channels that will be used. The settings are Primary, Secondary, Both or Disabled. The Optimal and Fail-Safe default settings are Primary.

ONBOARD FDC

This option enables the floppy drive controller on the PC board. The settings are Auto, Enabled or Disabled. The default setting is Auto.

ONBOARD SERIAL PORT1

This option enables serial port 1 on the board and specifies the based I/O port address for serial port 1.

The settings are Auto, 3F8h, 3E8h, 2F8h, 2E8h, or Disabled. The default setting is Auto.

ONBOARD SERIAL PORT2

This option enables serial port 2 on the board and specifies the base I/O port address for serial port 2.

The settings are Auto, 3F8h, 3E8h, 2F8h, 2E8h, or Disabled. The default setting is Auto.

ONBOARD PARALLEL PORT

This option enables the parallel port on the board and specifies the parallel port based I/O port address. The settings are Auto, 378h, 278h, 3BCh, or Disabled. The default setting is Auto.

PARALLEL PORT MODE

This option specifies the parallel port mode. ECP and EPP are both bi-directional data transfer schemes that adhere to the IEEE P1284 specifications. The settings are :

SETTING	DESCRIPTION
Normal	The normal parallel port mode is used. This is the default setting.
Bi-Dir	Use this setting to support bi-directional transfers on the parallel port.
EPP	The parallel port can be used with devices that adhere to the Enhanced Parallel Port (EPP) specification. EPP uses the existing parallel port signals to provide asymmetric bi-directional data transfer driven by the host device.
ECP	The parallel port can be used with devices that adhere to the Extended Capabilities Port (ECP) specification. ECP uses the DMA protocol to achieve transfer rates of approximately 2.5Mbs. ECP provides symmetric bi-directional communications.

PARALLEL PORT IRQ

Selects which IRQ is assigned to the parallel port. Available options are Auto, 5, or 7. The default is Auto.

PARALLEL PORT DMA

This option is only available if the setting for the Parallel Port Mode option is ECP.

The settings are Auto, None, DMA CH 0, DMA CH 1, DMA CH 2, or DMA CH 3. (CH = channel). The default setting is Disabled.

HARDWARE IO PORT BASE ADDRESS

This specifies the base address of the HAWK configuration and control registers. The permissible options are:

To be advised.

SERIAL PORT 2 MODE

Specifies whether the second serial port will be used as RS232 or RS485. Options are RS232 and RS485. The optimal and fail safe defaults are RS232.

RS485 DUPLEX MODE

Specifies whether the second serial port will be used as full or half duplex when running in RS485 mode. This option is only available when the options 'Serial Port 2 Mode' is set to RS485. The options are FULL or HALF. The Optimal and Fail Safe defaults are FULL.

DISKONCHIP 2000 SUPPORT

The HAWK supports the use of M-Systems DiskOnChip 2000 Flash Module, the notes below detail the use of the device, please consult the DOC user manual if any more detail is required.

PREFACE

This note describes how to integrate the DiskOnChip 2000 with PC compatible systems. The DiskOnChip 2000 is a single chip FlashDisk designed to plug into a standard 32-pin EEPROM socket. The DiskOnChip 2000 should be mapped into an 8KByte window in the BIOS expansion address space of the PC, which is usually located between address 0C0000H to 0EFFFFH.

The DiskOnChip 2000 contains a built-in copy of the M-Systems industry-standard TrueFFS software, which makes the DiskOnChip operate as a standard disk drive. The DiskOnChip 2000 can contain the operating system in it to allow systems to boot without a hard disk. The DiskOnChip 2000 can also be configured as the boot device in systems with a hard disk (see below "Configuring the DiskOnChip 2000 as the first drive").

The DiskOnChip is a self-contained device. The installation of the DiskOnChip does not require any software installation. The design of the DiskOnChip allows for full upward and downward compatibility. While available today in capacities of 2 to 72MBytes, future DiskOnChip devices with higher densities, will be fully compatible with standard DiskOnChip sockets. The basic design of the DiskOnChip actually supports an unlimited capacity.

OPERATING THE DISKONCHIP

INSTALLING THE DISKONCHIP 2000

When installing or removing the DiskOnChip, be sure to first touch a grounded surface to discharge any static electricity from your body. Use the following procedure to install the DiskOnChip:

1. Align pin 1 on the DiskOnChip with pin 1 of Flash socket.
2. Push the DiskOnChip into the socket carefully until it is fully seated.
3. Check to make sure the DiskOnChip is installed securely, and there are no bent pins.

Caution: The DiskOnChip may be permanently damaged if installed incorrectly!

4. To install the DiskOnChip as drive C on a system without a hard disk, set the CMOS setup of drive C to "not installed" (indicating that no physical magnetic disk is installed), and reboot the computer. The DiskOnChip 2000 will install as drive C. The DiskOnChip needs to be formatted with the System files in order for it to be a bootable drive. See "Configuring the DiskOnChip as the BOOT device" below.
5. To install the DiskOnChip as drive D on a system with a hard disk, just reboot the system, and the DiskOnChip will install as drive D.
6. To install the DiskOnChip as Drive C on a system with a hard disk, see below "Configuring the DiskOnChip as the first drive".

CONFIGURING THE DISKONCHIP 2000 AS THE BOOT DEVICE

In order to configure the DiskOnChip as the boot device, the operating system files need to be copied into it. Copying the operating system files into DiskOnChip Should be done like in any other hard disk. The following is an example of a typical initialization process:

1. Set the DiskOnChip as a regular drive in your system (not a boot drive).
2. Install a bootable floppy diskette in drive A and boot the system.
3. At the DOS prompt, type SYS C: to transfer the DOS system files to the DiskOnChip (assuming the DiskOnChip is installed as drive C).
4. Copy any files needed into the DiskOnChip.
5. Remove the floppy diskette and reboot the system. The system will boot from the DiskOnChip, and will allow you to run and access any files that have been copied into the DiskOnChip.

CONFIGURING THE DISKONCHIP 2000 AS THE FIRST DRIVE

The DiskOnChip can be configured to be installed as the last drive (default), or as the first drive in the system. When configured as the last drive, the DiskOnChip is installed as disk D if there is another hard drive installed, and as drive C if no other hard disk is installed. When configured as the first drive, the DiskOnChip is always installed as drive C. The DiskOnChip is shipped from the factory, configured to install as the last drive. To configure the DiskOnChip to be installed as the first drive, proceed as follows:

1. Boot the system and make sure the DiskOnChip is installed correctly as drive D
2. At the DOS prompt type: DUPDATE D: /FIRST /S:DOC2000.EXB
3. After re-booting the system, the DiskOnChip will appear as drive C:

ADDRESS MAPS

MEMORY MAP

ADDRESS RANGE (DECIMAL)	ADDRESS RANGE (HEX)	SIZE	DESCRIPTION
1024K - 131072K	100000 - 8000000	127M	Extended Memory
896K - 1023K	E0000 - FFFFF	128K	AMI System BIOS (not available for UMB)
880K - 895K	DC000 - DFFFF	16K	Solid State Disk Pages
848K - 879K	D4000 - DBFFF	32K	BIOS Extensions
800K - 847K	C8000 - D3FFF	48K	Available HI DOS memory (open to ISA and PCI bus)
640K - 799K	A0000 - C7FFF	160K	On-board video memory and BIOS
639K	9FC00 - 9FFFF	1K	Extended BIOS Data (moveable by QEMM, 386MAX)
512K - 638K	80000 - 9FBFF	127K	Extended conventional
0K - 511K	00000 - 7FFFF	512K	Conventional

I/O MAP

The following table lists the I/O addresses used by single board PC devices. Some of these devices (e.g. graphics) may not be present in all configurations. Some devices (serial ports, parallel ports etc.) may be configured for various addresses or disabled. These I/O locations are listed in the Variable Resources column.

ADDRESS (HEX)	SIZE Bytes	FIXED RESOURCES	VARIABLE RESOURCES
0000 - 000F	16	PIIIX - DMA 1	
0020 - 0021	2	PIIIX - Interrupt Controller 1	
002E - 002F	2	Ultra I/O configuration registers	
0040 - 0043	4	PIIIX - Timer 1	
0060	1	Keyboard Controller Data Byte	
0061	1	PIIIX - NMI, speaker control	
0064	1	Kbd Controller, CMD/STAT Byte	
0070, bit 7	1 bit	PIIIX - Enable NMI	
0070, bits 6:0	7 bits	RTC, Address	
0071	1	RTC, Data	
0080 - 008F	16	PIIIX - DMA Page Register	
00A0 - 00A1	2	PIIIX - Interrupt Controller 2	
00B2 - 00B3	2	PIIIX - APM Control / Status Interrupt Controller 2	
00C0 - 00DE	31	PIIIX - DMA 2	
00F0	1	Reset Numeric Error	
0100 - 0107	8	Reserved for Board Confign.	
0170 - 0177	8		
01F0 - 01F7	8		Primary IDE Channel
0200 - 0207	8		Gameport Joystick
0278 - 027B	4		Parallel Port 2
02E8 - 02EF	8		Serial Port 4
02F8 - 02FF	8		Serial Port 2
0376	1		
0377	1		
0378 - 037F	8		Parallel Port 1
03B0 - 03BB	4		C&T65545/8
03BC - 03BF	4		Parallel Port 3
03C0 - 03DF	16		C&T65545/8
03E8 - 03EF	8		Serial Port 3
03F0 - 03F5	6		Floppy Channel 1
03F6	1		Pri IDE Chan Cmnd Port
03F7 (Write)	1		Floppy Chan 1 Cmd
03F7, bit 7	1 bit		Floppy Disk Chg Chan 1
03F7, bits 6:0	7 bits		Pri IDE Chan Status Port
03F8 - 03FF	8		Serial Port 1
LPT + 400h	3		ECP regs, LPT base + 400h
04D0 - 04D1	2	Edge/Level INTR Control Reg.	
0CF8 - 0CFC*	4	PCI Config Address Reg.	
0CF9	1	Turbo & Reset control Reg.	
0CFC - 0CFF	4	PCI Config Data Reg	
FFA0 - FFA7	8		1ary Bus MasterIDE regs
FFA8 - FFAF	8		2ary Bus Master IDE regs
FF00-FF07	8		IDE Bus Master Reg.

*only accessible by DWORD accesses.

PCI CONFIGURATION SPACE MAP

The Triton chipset uses Configuration Mechanism 1 to access the PCI configuration space. The PCI Configuration Address register is a 32-bit I/O register located at 0CF8h, the PCI Configuration Data register is a 32-bit I/O register located at 0CFCh. The PCI Configuration Address register is only accessible by a DWORD access, the PCI Configuration Data register is accessible by DWORD, WORD or BYTE accesses.

ACCESS TO I/O CONFIGURATION SPACE USING MECHANISM #1

1. Using a DWORD write command, output the required I/O configuration address to I/O port CF8H
2. Using a DWORD read or write command, read or write data from the I/O port CFCH

NOTE: Any address output to CF8H is always on a 4 byte (DWORD) boundary. You can read or write any BYTE, WORD or DWORD in the four byte range by using the correct offset as follows:

DWORD @ CFCh

WORD @ CFCh or CFEh

BYTE @ CFCh, CFDh, CFEh or CFFh

CONFIGURATION ADDRESS REGISTER BIT DEFINITION

BIT	FUNCTION / SETTING
31	1
30 - 24	RESERVED
23 -16	BUS NUMBER
15 - 11	DEVICE NUMBER
10 - 8	FUNCTION NUMBER
7 - 2	REGISTER NUMBER
1	0
0	0

CONFIG SPACE ENABLE FLAG (Bit 31): Always 1 to indicate I/O access is to configuration space.

RESERVED (Bits 30-24): Always 00h

BUS NUMBER (Bits 23-16): Always 00h unless a bridge card is installed in a PCI slot

DEVICE NUMBER (Bits 15-11): Used to indicate a specific PCI device. The Triton TSC has a predefined device number of 00000h. The PIIIX and four PCI slots also have specific device numbers, that device number is determined by which PCI Address/Data line is connected to the device's ID SEL pin. Table E-1 details the specific mapping information.

FUNCTION NUMBER (Bits 10-8): Used to indicate a specific function in multifunction PCI devices. The PIIIX is the only multi-function device on HAWK located on the single board PC. Use 00h for the basic PIIIX device and 01h for the PCI IDE BUS MASTER FUNCTION. For a multi-function PCI add-in card, refer to the card's documentation to determine the allowable function numbers.

REGISTER NUMBER (Bits 7-2): Defines one of 64 DWORD locations for a specific PCI device.

Note that Bits 1 and 0 must always be 0h for DWORD access.

!!!!

The table below lists the PCI bus and device numbers used by the single board PC. It also lists the data range that must be written to the I/O Configuration Address register to access the device.

DEVICE	BUS/DEVICE / FUNCTION	ID SEL	I/O CONFIG ADDRESS REGISTER
TSC	00 / 00 / 0	N/A	8000 0000 - 8000 00FC
PIIIX	00 / 07 / 0	N/A	8000 3800 - 8000 38FC
PIIIX-IDE BUS MASTER	00 / 07 / 1	N/A	8000 3900 - 8000 39FC
C&T65545/8	00 / 08 / 0	AD18	8000 4000 - 8000 40FC
RTL8029/AS (Ethernet)	00 / 09 / 0	AD19	8000 4100 - 8000 41FC

INTERRUPTS & DMA CHANNELS

The following tables list the Interrupt and DMA Channel configuration **options** for on-board devices. The serial ports, parallel ports, and IDE controller can be configured using SETUP, or any other Plug and Play resource manager (such as the Windows™ 95 Device Manager). The Graphics interrupt is assigned by the auto-configure utility during boot up.

IRQ	RESERVED INTERRUPTS
NMI	I/O Channel Check
0	Interval Timer
1	Keyboard buffer full
2	Cascade interrupt from slave PIC
3	Serial 2 (COM2)
4	Serial 1 (COM1)
5	Parallel 2 (LPT2)
6	Floppy Controller
7	Parallel (LPT1)
8	Real time clock
9	
10	Monitor Micro (if present)
11	
12	PS/2 Mouse (if present)
13	Math co-processor
14	Primary E-IDE
15	

DMA	RESERVED
0	
1	
2	Floppy
3	
4	Cascade channel
5	
6	
7	

CONNECTORS

BACK PANEL CONNECTORS

The back panel houses the following connectors:

*VIDEO CONNECTOR **P18** (15 WAY CONDENSED D-TYPE)*

PIN NO.	SIGNAL	PIN NO.	SIGNAL
1	Analogue RED	2	Analogue GREEN
3	Analogue BLUE	4	Not Used
5	0 Volts (Ground)	6	0 Volts (Ground)
7	0 Volts (Ground)	8	0 Volts (Ground)
9	Not Used	10	0 Volts (Ground)
11	Not Used	12	Not Used
13	Horizontal Sync	14	Vertical Sync
15	Not Used		

*ECP/EPP PARALLEL PORT **P18 TOP** (26 WAY HEADER)*

PIN N°	SIGNAL	PIN N°	SIGNAL
1	-Strobe	2	-Auto Feed XT
3	Data bit 0	4	-Error
5	Data bit 1	6	-Initialise
7	Data bit 2	8	-Select (input)
9	Data bit 3	10	Ground
11	Data bit 4	12	Ground
13	Data bit 5	14	Ground
15	Data bit 6	16	Ground
17	Data bit 7	18	Ground
19	-Acknowledge	20	Ground
21	Busy	22	Ground
23	Paper Empty	24	Ground
25	Select (Output)	26	Not Used

*PS/2 MOUSE PORT **P21A** (BOTTOM 6 WAY MINI-DIN)*

PIN NO.	SIGNAL	PIN NO.	SIGNAL
1	Mouse Data	2	Not Used
3	Ground	4	+5 Volts (fused)
5	Mouse Clock	6	Not Used

*PS/2 KEYBOARD PORT **P21B** (TOP 6 WAY MINI-DIN)*

PIN NO.	SIGNAL	PIN NO.	SIGNAL
1	Keyboard Data	2	Not Used
3	Ground	4	+5 Volts (fused)
5	Keyboard Clock	6	Not Used

*RS232 SERIAL PORT 1 **P20A** (BOTTOM 9 WAY D-TYPE)*

PIN NO.	SIGNAL	PIN NO.	SIGNAL
1	Data Carrier Detect	2	-Receive Data
3	-Transmit Data	4	-Data Terminal Ready
5	Ground	6	-Data Set Ready
7	-Ready To Send	8	-Clear To Send
9	-RI or POWER		

*RS232 SERIAL PORT 2 **P20B** (TOP 9 WAY D-TYPE)*

PIN NO.	SIGNAL	PIN NO.	SIGNAL
1	Data Carrier Detect	2	-Receive Data
3	-Transmit Data	4	-Data Terminal Ready
5	Ground	6	-Data Set Ready
7	-Ready To Send	8	-Clear To Send
9	-RI or POWER		

*DUAL USB PORT 1 **P19 A** (BOTTOM 8 WAY)*

PIN NO.	SIGNAL	PIN NO.	SIGNAL
1	VCC	2	DATA1-
3	DATA1+	4	Ground

*DUAL USB PORT 2 **P19 B** (TOP 8 WAY)*

PIN NO.	SIGNAL	PIN NO.	SIGNAL
1	VCC	2	DATA2-
3	DATA2+	4	Ground

*ETHERNET UTP CONNECTOR **P22** (8 WAY RJ45)*

PIN N°	SIGNAL
1	+VE TRANSMIT
2	-VE TRANSMIT
3	+VE RECEIVE
4	NC
5	NC
6	-VE RECEIVE
7	NC
8	NC

INTERNAL I/O HEADERS

The board has a number of internal peripheral connectors:

*PRIMARY E-IDE CONNECTOR **P**13 (40 WAY HEADER)*

PIN NO.	SIGNAL	PIN NO.	SIGNAL
1	-Reset	2	Ground
3	Data bit 7 (HD)	4	Data bit 8 (HD)
5	Data bit 6 (HD)	6	Data bit 9 (HD)
7	Data bit 5 (HD)	8	Data bit 10 (HD)
9	Data bit 4 (HD)	10	Data bit 11 (HD)
11	Data bit 3 (HD)	12	Data bit 12 (HD)
13	Data bit 2 (HD)	14	Data bit 13 (HD)
15	Data bit 1 (HD)	16	Data bit 14 (HD)
17	Data bit 0 (HD)	18	Data bit 15 (HD)
19	Ground	20	Not used
21	Drive Request	22	Ground
23	-IO Write (HD)	24	Ground
25	-IO Read (HD)	26	Ground
27	Drive Ready	28	Not Used
29	Drive Acknowledge	30	Ground
31	IRQ14	32	Not Used
33	Address 1 (HD)	34	1 Kohm to Ground
35	Address 0 (HD)	36	Address 2 (HD)
37	-Chip Select 0 (HD)	38	-Chip Select 1 (HD)
39	IDE LED Drive	40	Ground

*LCD CONNECTOR **P**11 (50 WAY 2MM HEADER)*

PIN NO.	SIGNAL	PIN NO.	SIGNAL
1	5V/3V3 Link (J15)	2	Vertical Sync
3	Switched +12 volts	4	Ground
5	Switched VEE	6	Horizontal Sync
7	Switched +5 volts	8	Ground
9	Switched +5 volts	10	General Purpose 1
11	Shift Clock	12	Ground
13	Line Clock	14	General Purpose 0
15	MOD	16	Ground
17	FLM (LCD equivalent of VSYNC)	18	Ground
19	Panel Data 0	20	Ground
21	Panel Data 1	22	Panel Data 23
23	Panel Data 2	24	Ground
25	Panel Data 3	26	Panel Data 22
27	Panel Data 4	28	Ground
29	Panel Data 5	30	Panel Data 21
31	Panel Data 6	32	Ground
33	Panel Data 7	34	Panel Data 20
35	Panel Data 8	36	Ground
37	Panel Data 9	38	Panel Data 19
39	Panel Data 10	40	Ground
41	Panel Data 11	42	Panel Data 18
43	Panel Data 12	44	Ground
45	Panel Data 13	46	Panel Data 17
47	Panel Data 14	48	Ground
49	Panel Data 15	50	Panel Data 16

*AUDIO VOLUME CONTROL **P6** (4 WAY PIN HEADER)*

Pin N°	Signal	Pin N°	Signal
1	Mute	2	Volume Up
3	Volume Down	4	Audio Ground

*CD-AUDIO INPUT **P7** (4 WAY PIN HEADER)*

Pin N°	Signal	Pin N°	Signal
1	CD Audio In Left	2	Audio Ground
3	CD Audio In Right	4	Audio Ground

*AUDIO CONNECTOR **P8** (8 WAY HEADER)*

Pin N°	Signal	Pin N°	Signal
1	Line In Left	2	Line In Right
3	Audio Ground	4	Audio Ground
5	Microphone In	6	Not Used
7	Audio Ground	8	Audio Ground
9	Line Out Left	10	Line Out Right

*FLOPPY DISK DRIVE CONNECTOR **P12** (34 WAY HEADER)*

PIN N°	SIGNAL	PIN N°	SIGNAL
1	Ground	2	+RPM/Low Current
3	Ground	4	Not used
5	Ground	6	Not used
7	Ground	8	-Index
9	Ground	10	-Motor 0
11	Ground	12	-Drive select 1
13	Ground	14	-Drive select 0
15	Ground	16	-Motor 1
17	Ground	18	+Direction
19	Ground	20	-Step
21	Ground	22	-Write Data
23	Ground	24	-Write Gate
25	Ground	26	-Track 0
27	Ground	28	-Write Protect
29	Ground	30	-Read Data
31	Ground	32	+Head Select
33	Ground	34	+Disk Change

*RS485 SERIAL PORT 2 **P14** (10 WAY HEADER)*

PIN NO.	SIGNAL	PIN NO.	SIGNAL
1	+Rx FDX	2	+Term. 10 K to +5V
3	-Rx FDX	4	No Connect
5	+Tx FDX, +Rx/+Tx HDX	6	No Connect
7	-Tx FDX, -RX/-Tx HDX	8	No Connect
9	-Term. 10 K to Gnd	10	No Connect

*RS232 SERIAL PORT 3 **P15** (10 WAY HEADER)*

Pin N°	Signal	Pin N°	Signal
1	-Data Carrier Detect	2	-Data Set Ready
3	-Receive Data	4	-Ready To Send
5	-Transmit Data	6	-Clear To Send
7	-Data Term Ready	8	-RI or POWER
9	Ground	10	Not used

*RS232 SERIAL PORT 4 **P17** (10 WAY HEADER)*

Pin N°	Signal	Pin N°	Signal
1	-Data Carrier Detect	2	-Data Set Ready
3	-Receive Data	4	-Ready To Send
5	-Transmit Data	6	-Clear To Send
7	-Data Term Ready	8	-RI or POWER
9	Ground	10	Not used

*SUPERVISORY CONNECTOR **P24** (5 WAY 2MM HEADER)*

Pin N°	Signal	Pin N°	Signal
1	Analogue I/P 0 or Magstripe Clock	2	Analogue I/P 1 or Magstripe Data
3	Ground	4	+5 volts
5	Not Used or -Card Present		

The usage of pins on this connector depends on the version of microcontroller fitted at the factory. Please check with your supplier for further details.

*POWER CONNECTOR **P4** (34 WAY HEADER)*

PIN N°	SIGNAL
1	Note 1
2	+5V
3	+12V
4	-12V
5	Ground
6	Ground
7	Ground
8	Ground
9	-5V
10	+5V
11	+5V
12	+5V

Note 1: This signal is normally used as POWER GOOD from the PSU. On Hawk this pin has been reserved for +24V connection which is re-routed to a link selectable output on the serial ports. It is required by some customers for powering external devices via the serial port. The link options for these ports are +24V, +12V, +5V (all fused at 2A) or RI (Ring Indicator). If this option is not required then either leave the power pin on P4 disconnected or connect the POWER GOOD signal from the PSU (as per the standard PC PSU) and set the serial port jumpers to RI. The RI signal will then appear on pin 9 of the COM port D type connectors.

*UTILITY CONNECTOR **P16** (20 WAY HEADER)*

PIN N°	SIGNAL	PIN N°	SIGNAL
1	Audio +ve	2	Audio -ve
3	Reset +ve	4	Reset -ve (Ground)
5	Watchdog LED +ve	6	Watchdog LED -ve
7	Keylock +ve	8	Keylock -ve (Ground)
9	Power LED +ve	10	Power LED -ve (Ground)
11	External SMI +ve	12	External SMI -ve (Ground)
13	IDE LED +ve	14	IDE LED -ve
15	+5V (fused)	16	0 Volts (Ground)
17	External +3.6 Volt Battery	18	0 Volts Battery (Ground)
19	Keyboard Data	20	Keyboard Clock

*COAST CACHE CONNECTOR **P3***

This is an industry-standard connector for **C**ache **O**n **A** **St**ick. The COAST connector is a 160-pin socket which is designed to prevent reversed fitting of the cache module.

Please note that each cache module is designed specifically for each chipset i.e. there are cache modules specific to the 430HX Triton chipset. The available options for HAWK cache are 256kbyte asynchronous, 256 or 512KByte of synchronous Pipeline burst, or none.

*BATTERY CONNECTOR **P1** (4 WAY HEADER)*

Pin N°	Signal
1	+3.6 Volts DC
2	Not used (key)
3	Ground
4	Ground

BUS CONNECTORS

ISA BUS XT CONNECTIONS

A= Large gold fingers on **main** component side
B= Large gold fingers on reverse side

PIN NO.	SIGNAL	PIN NO.	SIGNAL
A1	-IOCHCK	B1	Ground
A2	SD7	B2	Resetdrv
A3	SD6	B3	+5 Volts
A4	SD5	B4	IRQ9
A5	SD4	B5	-5 Volts
A6	SD3	B6	DREQ2
A7	SD2	B7	-12 Volts
A8	SD1	B8	-0WS
A9	SD0	B9	+12 Volts
A10	IOCHRDY	B10	Ground
A11	AEN	B11	-SMEMW
A12	SA19	B12	-SMEMR
A13	SA18	B13	-IOW
A14	SA17	B14	-IOR
A15	SA16	B15	-DACK3
A16	SA15	B16	DREQ3
A17	SA14	B17	-DACK1
A18	SA13	B18	DREQ1
A19	SA12	B19	-REF
A20	SA11	B20	CLK
A21	SA10	B21	IRQ7
A22	SA9	B22	IRQ6
A23	SA8	B23	IRQ5
A24	SA7	B24	IRQ4
A25	SA6	B25	IRQ3
A26	SA5	B26	-DACK2
A27	SA4	B27	T/C
A28	SA3	B28	BALE
A29	SA2	B29	+5 Volts
A30	SA1	B30	OSC
A31	SA0	B31	Ground

ISA BUS AT CONNECTIONS

C= Large gold fingers on **main** component side

D= Large gold fingers on reverse side

PIN NO.	SIGNAL	PIN NO.	SIGNAL
C1	-SBHE	D1	-MEMCS16
C2	LA23	D2	-IOCS16
C3	LA22	D3	IRQ10
C4	LA21	D4	IRQ11
C5	LA20	D5	IRQ12
C6	LA19	D6	IRQ15
C7	LA18	D7	IRQ14
C8	LA17	D8	-DACK0
C9	-MEMR	D9	DREQ0
C10	-MEMW	D10	-DACK5
C11	SD8	D11	DREQ5
C12	SD9	D12	-DACK6
C13	SD10	D13	DREQ6
C14	SD11	D14	-DACK7
C15	SD12	D15	DREQ7
C16	SD13	D16	+5 Volts
C17	SD14	D17	-Master
C18	SD15	D18	Ground

*PC104 PC/XT CONNECTOR **P5** (64 WAY SOCKET)*

SIDE A	SIGNAL	SIDE B	SIGNAL
1	-IOCHCK	1	Ground
2	SD7	2	Resetdrv
3	SD6	3	+5 Volts
4	SD5	4	IRQ9
5	SD4	5	-5 Volts
6	SD3	6	DREQ2
7	SD2	7	-12 Volts
8	SD1	8	-0WS
9	SD0	9	+12 Volts
10	IOCHRDY	10	Ground
11	AEN	11	-SMEMW
12	SA19	12	-SMEMR
13	SA18	13	-IOW
14	SA17	14	-IOR
15	SA16	15	-DACK3
16	SA15	16	DREQ3
17	SA14	17	-DACK1
18	SA13	18	DREQ1
19	SA12	19	-REF
20	SA11	20	CLK
21	SA10	21	IRQ7
22	SA9	22	IRQ6
23	SA8	23	IRQ5
24	SA7	24	IRQ4
25	SA6	25	IRQ3
26	SA5	26	-DACK2
27	SA4	27	T/C
28	SA3	28	BALE
29	SA2	29	+5 Volts
30	SA1	30	OSC
31	SA0	31	Ground
32	Ground	32	Ground

*PC104 PC/AT CONNECTOR **P9** (40 WAY SOCKET)*

SIDE C	SIGNAL	SIDE D	SIGNAL
1	Ground	1	Ground
2	-SBHE	2	-MEMCS16
3	LA23	3	-IOCS16
4	LA22	4	IRQ10
5	LA21	5	IRQ11
6	LA20	6	IRQ12
7	LA19	7	IRQ15
8	LA18	8	IRQ14
9	LA17	9	-DACK0
10	-MEMR	10	DREQ0
11	-MEMW	11	-DACK5
12	SD8	12	DREQ5
13	SD9	13	-DACK6
14	SD10	14	DREQ6
15	SD11	15	-DACK7
16	SD12	16	DREQ7
17	SD13	17	+5 Volts
18	SD14	18	-Master
19	SD15	19	Ground
20	No Connection	20	Ground

DIGITAL IO CONNECTOR P25 (20 WAY HEADER)

Pin No	Signal	Pin No	Signal
1	Vcc (via 22R)	2	Vcc (via 22R)
3	Digital Out 0	4	Digital In 0
5	Digital Out 1	6	Digital In 1
7	Digital Out 2	8	Digital In 2
9	Digital Out 3	10	Digital In 3
11	Digital Out 4	12	Digital In 4
13	Digital Out 5	14	Digital In 5
15	Digital Out 6	16	Digital In 6
17	Digital Out 7	18	Digital In 7
19	Ground	20	Ground

ERROR MESSAGES

AMIBIOS ERROR BEEP CODES

The BIOS performs a **P**ower **O**n **S**elf **T**est (POST) after a reset or reboot. If errors occur during the POST, the microprocessor indicates the status of the test by writing codes to the I/O port at address 80 Hex. If the BIOS cannot find and configure the display controller then the errors are communicated through a series of audible beeps (by the speaker drive circuit). Fatal errors, which prevent the system from continuing the boot process, will produce beep codes.

Other errors are displayed textually. For these see AMIBIOS Error Messages, in the following subsection.

BEEPS	ERROR MESSAGE	DESCRIPTION
1long, 3 short	Video failure	A connection to a monitor was not detected.
1	Refresh Failure	The memory refresh circuitry on the single board PC is faulty.
2	Parity Error	Parity is not supported on this product, will not occur.
3	Base 64 KB Memory Failure	Memory failure in the first 64 KB.
4	Timer Not Operational	Memory failure in the first 64 KB of memory, or Timer 1 on the single board PC is not functioning.
5	Processor Error	The CPU on the single board PC generated an error.
6	8042 - Gate A20 Failure	The keyboard controller (8042) may be bad. The BIOS cannot switch to protected mode.
7	Processor Exception Interrupt Error	The CPU generated an exception interrupt.
8	Display Memory Read/Write Error	System video adapter is either missing or its memory is faulty. This is not a fatal error.
9	ROM Checksum Error	ROM checksum value does not match the value encoded in BIOS.
10	CMOS Shutdown Register Rd/Wrt Error	The shutdown register for CMOS RAM failed.
11	Cache Error / External Cache Bad	The external cache is faulty.

AMIBIOS ERROR CODES ON THE POST DISPLAY

As the BIOS performs the POST after a reset or reboot, the microprocessor indicates the status of the test by writing codes to the I/O port at address 80 Hex. HAWK provides an on-board decode of this information displaying the code on on-board LEDs. It can also drive an optional POST display without modification. The following codes indicate the progress of the microprocessor during the power on test.

UNCOMPRESSED INIT CODE CHECKPOINTS

CODE (HEX)	DESCRIPTION
D0	NMI is Disabled. CPU ID saved. Init code Checksum verification starting.
D1	To do DMA init, Keyboard controller BAT test, start memory refresh and going to 4GB flat mode.
D3	To start Memory sizing.
D4	To come back to real mode. Execute OEM patch. Set stack.
D5	E000 ROM enabled. Init code is copied to segment 0 and control to be transfered to segment 0.
D6	Control is in segment 0. To check <CTRL><HOME> key and verify main BIOS checksum. If either <CTRL><HOME> is pressed or main BIOS checksum is bad, go to check point E0 else goto check point D7.
D7	Main BIOS runtime code is to be decompressed and control to be passed to main BIOS in shadow RAM.

BOOT BLOCK RECOVERY CODE CHECKPOINTS

CODE (HEX)	DESCRIPTION
E0	On-Board Floppy Controller (if any) is initialised. To start base 512K memory test.
E1	To initialise interrupt vector table.
E2	To initialise DMA and interrupt controllers.
E6	To enable floppy and timer IRQ, enable internal cache.
ED	Initialize floppy drive.
EE	Start looking for a diskette in drive A: and read 1st sector of the diskette.
EF	Floppy read error.
F0	Start searching 'AMIBOOT.ROM' file in root directory.
F1	'AMIBOOT.ROM' file not present in root directory.
F2	Start reading FAT table and analyze FAT to find the clusters occupied by 'AMIBOOT.ROM' file..
F3	Start reading 'AMIBOOT.ROM' file cluster by cluster.
F4	'AMIBOOT.ROM' file not of proper size.
F5	Disable internal cache.
FB	Detect Flash type present.
FC	Erase Flash.
FD	Program Flash.
FF	Flash program successful. BIOS is going to restart.

RUNTIME CODE IS UNCOMPRESSED IN F000 SHADOW RAM

CODE (HEX)	DESCRIPTION
03	NMI is Disabled. To check soft reset/power-on.
05	BIOS stack set. Going to disable Cache if any.
06	POST code to be uncompressed.
07	CPU init and CPU data area init to be done.
08	CMOS checksum calculation to be done next.
0B	Any initialisation before keyboard BAT to be done next.
0C	KB controller I/B free. To issue the BAT command to keyboard controller.
0E	Any initialisation after KB controller BAT to be done next.
0F	Keyboard command byte to be written.
10	Going to issue Pin-23,24 blocking/unblocking command.
11	Going to check pressing of <INS> , <END> key during power-on.
12	To init CMOS if “Init CMOS in every boot” is set or <END> key is pressed. Going to disable DMA and Interrupt controllers.
13	Video display is disabled and port-B is initialised. Chipset init about to begin.
14	8254 timer test about to start.
19	About to start memory refresh test.
1A	Memory Refresh line is toggling. Going to check 15us ON/OFF time.
23	To read 8042 input port and disable Megakey GreenPC feature. Make BIOS code segment writeable.
24	To do any setup before Int vector init.
25	Interrupt vector initialisation about to begin. To clear password if necessary.
27	Any initialisation before setting video mode to be done.
28	Going for monochrome mode and colour mode setting.
2A	Different BUSes init (system, static, output devices) to start if present.
2B	To give control for any setup required before optional video ROM check.
2C	To look for optional video ROM and give control.
2D	To give control to do any processing after video ROM returns control.
2E	If EGA/VGA not found then do display memory R/W test.
2F	EGA/VGA not found. Display memory R/W test about to begin.
30	Display memory R/W test passed. About to look for the retrace checking.
31	Display memory R/W test or retrace checking failed. To do alternate Display memory R/W test.
32	Alternate Display memory R/W test passed. To look for the alternate display retrace checking.
34	Video display checking over. Display mode to be set next.
37	Display mode set. Going to display the power on message.
38	Different BUSes init (input, IPL, general devices) to start if present.
39	Display different BUSes initialisation error messages.
3A	New cursor position read and saved. To display the Hit <DEL> message.
40	To prepare the descriptor tables.
42	To enter in virtual mode for memory test.
43	To enable interrupts for diagnostics mode.

CODE (HEX)	DESCRIPTION
44	To Initialize data to check memory wrap around at 0:0.
45	Data initialised. Going to check for memory wrap around at 0:0 and finding the total system memory size.
46	Memory wrap around test done. Memory size calculation over. About to go for writing patterns to test memory.
47	Pattern to be tested written in extended memory. Going to write patterns in base 640k memory.
48	Patterns written in base memory. Going to find out amount of memory below 1M memory.
49	Amount of memory below 1M found and verified. Going to find out amount of memory above 1M memory.
4B	Amount of memory above 1M found and verified. Check for soft reset and going to clear memory below 1M for soft reset. (If power on, go to check point# 4Eh).
4C	Memory below 1M cleared. (SOFT RESET) Going to clear memory above 1M.
4D	Memory above 1M cleared. (SOFT RESET) Going to save the memory size. (Goto check point# 52h).
4E	Memory test started. (NOT SOFT RESET) About to display the first 64k memory size.
4F	Memory size display started. This will be updated during memory test. Going for sequential and random memory test.
50	Memory testing/initialisation below 1M complete. Going to adjust displayed memory size for relocation/ shadow.
51	Memory size display adjusted due to relocation/ shadow. Memory test above 1M to follow.
52	Memory testing/initialisation above 1M complete. Going to save memory size information.
53	Memory size information is saved. CPU registers are saved. Going to enter in real mode.
54	Shutdown successful, CPU in real mode. Going to disable gate A20 line and disable parity/NMI.
57	A20 address line, parity/NMI disable successful. Going to adjust memory size depending on relocation/shadow.
58	Memory size adjusted for relocation/shadow. Going to clear Hit <DEL> message.
59	Hit <DEL> message cleared. <WAIT...> message displayed. About to start DMA and interrupt controller test.
60	DMA page register test passed. To do DMA#1 base register test.
62	DMA#1 base register test passed. To do DMA#2 base register test.
65	DMA#2 base register test passed. To program DMA unit 1 and 2.
66	DMA unit 1 and 2 programming over. To Initialize 8259 interrupt controller.
7F	Extended NMI sources enabling is in progress.
80	Keyboard test started. clearing output buffer, checking for stuck key, to issue keyboard reset command.
81	Keyboard reset error/stuck key found. To issue keyboard controller interface test command.

CODE (HEX)	DESCRIPTION
82	Keyboard controller interface test over. To write command byte and init circular buffer.
83	Command byte written, Global data init done. To check for lock-key.
84	Lock-key checking over. To check for memory size mismatch with CMOS.
85	Memory size check done. To display soft error and check for password or bypass setup.
86	Password checked. About to do programming before setup.
87	Programming before setup complete. To uncompress SETUP code and execute CMOS setup.
88	Returned from CMOS setup program and screen is cleared. About to do programming after setup.
89	Programming after setup complete. Going to display power on screen message.
8B	First screen message displayed. <WAIT...> message displayed. PS/2 Mouse check and extended BIOS data area allocation to be done.
8C	Setup options programming after CMOS setup about to start.
8D	Going for hard disk controller reset.
8F	Hard disk controller reset done. Floppy setup to be done next.
91	Floppy setup complete. Hard disk setup to be done next.
95	Init of different BUSes optional ROMs from C800 to start.
96	Going to do any init before C800 optional ROM control.
97	Any init before C800 optional ROM control is over. Optional ROM check and control will be done next.
98	Optional ROM control is done. About to give control to do any required processing after optional ROM returns control and enable external cache.
99	Any initialisation required after optional ROM test over. Going to setup timer data area and printer base address.
9A	Return after setting timer and printer base address. Going to set the RS-232 base address.
9B	Returned after RS-232 base address. Going to do any initialisation before Coprocessor test
9C	Required initialisation before Coprocessor is over. Going to Initialize the Coprocessor next.
9D	Coprocessor initialised. Going to do any initialisation after Coprocessor test.
9E	Initialisation after Coprocessor test is complete. Going to check extd keyboard, keyboard ID and num-lock. Keyboard ID command to be
A2	Going to display any soft errors.
A3	Soft error display complete. Going to set keyboard typematic rate.
A4	Keyboard typematic rate set. To program memory wait states.
A5	Going to enable parity/NMI.
A7	NMI and parity enabled. Going to do any initialisation required before giving control to optional ROM at E000.
A8	Initialisation before E000 ROM control over. E000 ROM to get control next.

A9	Returned from E000 ROM control. Going to do any initialisation required after E000 optional ROM control.
AA	Initialisation after E000 optional ROM control is over. Going to display the system configuration.
AB	To uncompress DMI data and execute DMI POST init.
B0	System configuration is displayed.
B1	Going to copy any code to specific area.
00	Copying of code to specific area done. Going to give control to INT-19 boot loader.

AMIBIOS ERROR MESSAGES

Textual error messages are displayed in the following format:

ERROR Message Line 1
ERROR Message Line 2

For most displayed error messages, there is only one message. If a second message appears, it is "RUN SETUP". If this message occurs, press <F1> to run Setup Utility. The table of messages is shown on the next page.

ERROR MESSAGE	EXPLANATION
8042 Gate - A20 Error	Gate A20 on the keyboard controller (8042) is not working. Replace the 8042.
Address Line Short!	Error in the address decoding circuitry on the single board PC.
Cache Memory Bad, Do Not Enable Cache!	Cache memory is defective. Replace it.
CH-2 Timer Error	Most AT systems include two timers. There is an error in timer 2.
CMOS Battery State Low	CMOS RAM is powered by a battery. The battery power is low. Replace the battery.
CMOS Checksum Failure	After CMOS RAM values are saved, a checksum value is generated for error checking. The previous value is different from the current value. Run AMIBIOS Setup.
CMOS System Options Not Set	The values stored in CMOS RAM are either corrupt or non-existent. Run Setup.
CMOS Display Type Mismatch	The video type in CMOS RAM does not match the type detected by the BIOS. Run AMIBIOS Setup.
CMOS Memory Size Mismatch	The amount of memory on the single board PC is different than the amount in CMOS RAM. Run AMIBIOS Setup.
CMOS Time and Date Not Set	Run Standard CMOS Setup to set the date and time in CMOS RAM.
Diskette Boot Failure	The boot disk in floppy drive A: is corrupt. It cannot be used to boot the system. Use another boot disk and follow the screen instructions.
Display Switch Not Proper	The display jumper is not implemented on this product, this error will not occur.
DMA Error	Error in the DMA controller.
DMA #1 Error	Error in the first DMA channel.
DMA #2 Error	Error in the second DMA channel.
FDD Controller Failure	The BIOS cannot communicate with the floppy disk drive controller. Check all appropriate connections after the system is powered down.
HDD Controller Failure	The BIOS cannot communicate with the hard disk drive controller. Check all appropriate connections after the system is powered down.
INTR #1 Error	Interrupt channel 1 failed POST.
INTR #2 Error	Interrupt channel 2 failed POST.
Invalid Boot Diskette	The BIOS can read the disk in floppy drive A:, but cannot boot the system. Use another boot disk.
Keyboard Is Locked...Unlock It	The keyboard lock on the system is engaged. The system must be unlocked to continue.
Keyboard Error	There is a timing problem with the keyboard. Set the *Keyboard* option in Standard CMOS Setup to *Not Installed* to skip the keyboard POST routines.
KB/Interface Error	There is an error in the keyboard connector.
Off Board Parity Error	Parity error in memory installed in an expansion slot. The format is: OFF BOARD PARITY ERROR ADDR (HEX) = (XXXX) Where “XXXX” is the hex address where the error occurred.
On Board Parity Error	Parity is not supported on this product, this error will not occur.
Parity Error ????	Parity error in system memory at an unknown address.

ISA NMI MESSAGES

ISA NMI MESSAGE	EXPLANATION
Memory Parity Error at XXXXX	Memory failed. If the memory location can be determined, it is displayed as XXXXX. If not, the message is *Memory Parity Error ????*.
I/O Card Parity Error at XXXXX	An expansion card failed. If the address can be determined, it is displayed as XXXXX. If not, the message is *I/O Card Parity Error ????*.
DMA Bus Time-out	A device has driven the bus signal for more than 7.8 microseconds.

PCI CONFIGURATION ERROR MESSAGES

The following PCI messages are displayed as a group with bus, device and function information.

<'NVRAM Checksum Error, NVRAM Cleared'>, \ ; String

<'System Board Device Resource Conflict'>, \ ; String

<'Primary Output Device Not Found'>, \ ; String

<'Primary Input Device Not Found'>, \ ; String

<'Primary Boot Device Not Found'>, \ ; String

<'NVRAM Cleared By Jumper'>, \ ; String

<'NVRAM Data Invalid, NVRAM Cleared'>, \ ; String

<'Static Device Resource Conflict'>, \ ; String

The following messages chain together to give a message such as:

"PCI I/O Port Conflict: Bus: 00, Device 0D, Function: 01".

If and when more than 15 PCI conflict errors are detected, the log full message is displayed.

<'PCI I/O Port Conflict:'>, \ ; String

<'PCI Memory Conflict: '>, \ ; String

<'PCI IRQ Conflict: '>, \ ; String

<' Bus '>, \ ; String

<', Device '>, \ ; String

<', Function '>, \ ; String

<'PCI Error Log is Full.'>, \ ; String

<'Floppy Disk Controller Resource Conflict '>, \ ; Text

<'Primary IDE Controller Resource Conflict '>, \ ; Text

<'Secondary IDE Controller Resource Conflict '>, \ ; Text

<'Parallel Port Resource Conflict '>, \ ; Text

<'Serial Port 1 Resource Conflict '>, \ ; Text

<'Serial Port 2 Resource Conflict '>, \ ; Text

BOARD LAYOUT